
PISO-DNM100-D/T PISO-DNM100U-D/T DeviceNet Master PCI Board User's Manual

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Revision

Version	Firmware Version	Date	Author	Description
3.1	2.4	2011 01/10	Johney	Add new functions * DNM100_ReadInputArea * DNM100_WriteOutputArea * DNM100_ReadbackOutputArea
3.0	2.2	2009/ 12/25	Johney	Add the information of the PISO-DNM100U board.
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1. General Information

1.1 DeviceNet Introduction

The CAN (Controller Area Network) is a serial communication protocol, which efficiently supports distributed real-time control with a very high level of security. It is an especially suited for networking "intelligent" devices as well as sensors and actuators within a system or sub-system. In CAN networks, there is no addressing of subscribers or stations in the conventional sense, but instead, prioritized messages are transmitted. DeviceNet is one kind of the network protocols based on the CAN bus and mainly used for machine control network, such as textile machinery, printing machines, injection molding machinery, or packaging machines, etc. DeviceNet is a low level network that provides connections between simple industrial devices (sensors, actuators) and higher-level devices (controllers), as shown in Figure 1.1.

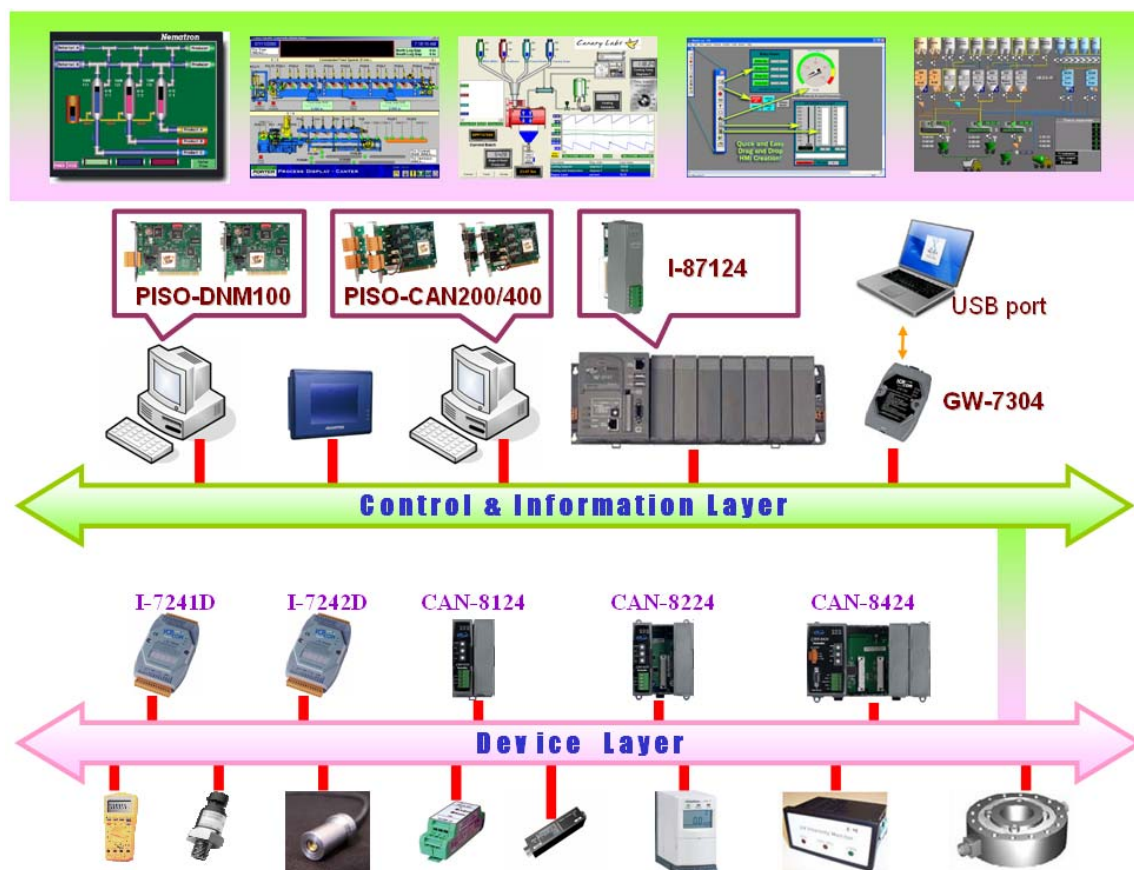


Figure 1.1 Example of the DeviceNet network

DeviceNet is a cost effective solution to one kind application of control c\area network. It reduces the connection wires between devices and provides rapid troubleshooting rejection function. The transfer rate can be up to 500Kbps within 100 meters. The transfer distance can be up to 500 meters in 125Kbps (See Table 1.1). It allows direct peer to peer data exchange between nodes in an organized and, if necessary, deterministic manner. Master/Slave connection model can be supported in the same network. Therefore, DeviceNet is able to facilitate all application communications based on a redefine a connection scheme. However, DeviceNet connection object strands as the communication path between multiple endpoints, which are application objects that is needed to share data.

Baud rate (bit/s)	Max. Bus length (m)
500 K	100
250 K	250
125 K	500

Table 1.1 The Baud rate and the Bus length

PISO-DNM100(U) can represent an economic solution of DeviceNet application and be a DeviceNet master device on the DeviceNet network. PISO-DNM100(U) supports Group 2 only Server and UCMM functions to communication with slave devices. It has an independent CAN bus communication port with the ability to cover a wide range of DeviceNet applications. Besides, PISO-DNM100(U) uses the new CAN controller Phillips SJA1000T and transceiver 82C250, which provide bus arbitration, error detection with auto correction and re-transmission function. It can be installed on almost any windows-based system, for example Win98/Win2000/WinXP/WinNT. It is popularly applied in the industrial automation, building automation, vehicle, marine, and embedded control network. Therefore, that is an easy way to develop the DeviceNet network with PISO-DNM100(U).

1.2 DeviceNet Applications

DeviceNet is the standardized network application layer optimized for factory automation. It is mainly used in low- and mid-volume automation systems. Some users have also implemented DeviceNet for machine control systems. The main DeviceNet application fields include the following application area (For more information, please refer to www.odva.org):

- Production cell builds and tests CPUs
- Beer brewery
- Equipment for food packing
- Fiberglass twist machine
- Sponge production plant
- Isolation wall manufacturing
- Overhead storage bin production
- Pocket-bread bakery
- Dinnerware production
- HVAC module production
- Textile machines
- Trawler automation system
- LCD manufacturing plant
- Rolling steel door production
- Bottling line
- Tight manufacturing



1.3 PISO-DNM100(U) Architecture

The PISO-DNM100(U) provides users to establish DeviceNet network rapidly by Master/Slave connection model. The PISO-DNM100(U) is a high-performance DeviceNet master board with one CPU inside. This architecture of the PISO-DNM100(U) almost doesn't cost CPU resource and really increases the work efficiency on DeviceNet network. Applying the PISO-DNM100(U), users don't need to take care of the detail of the DeviceNet protocol. The inside firmware implements the DeviceNet protocol to help users to establish the connection with DeviceNet slave devices easily. The illustration about the idea is shown as Figure 1.2.

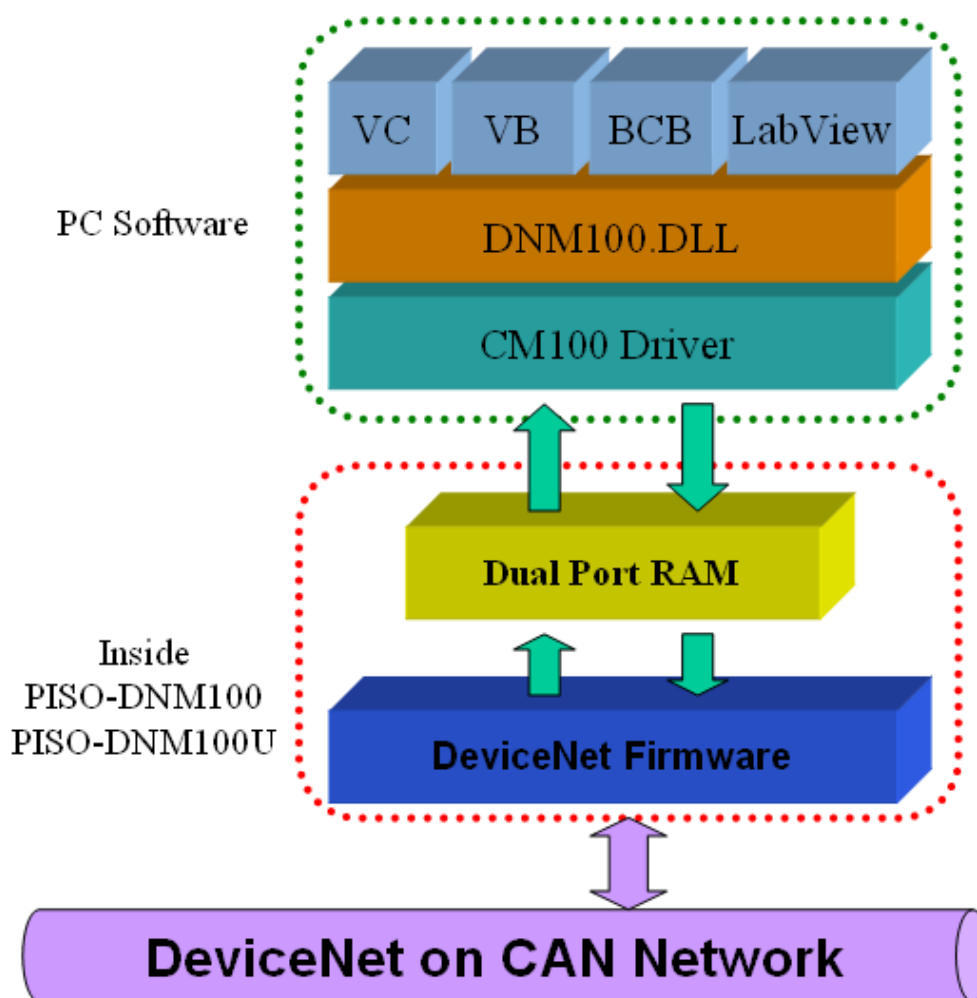


Figure 1.2 PISO-DNM100(U) illustration.

1.4 DeviceNet Master Characteristics

Using the API functions, users don't need to take care of the detail of the DeviceNet protocol. It can reduce the complexity of user's DeviceNet Master Software. The firmware mainly supports the Predefined Master-Slave Connection Set and UCMM functions to allow users to merge third party's DeviceNet devices into the DeviceNet network. It can help users to establish the connection with DeviceNet slave devices easily. The general application architecture is demonstrated as Figure 1.3.

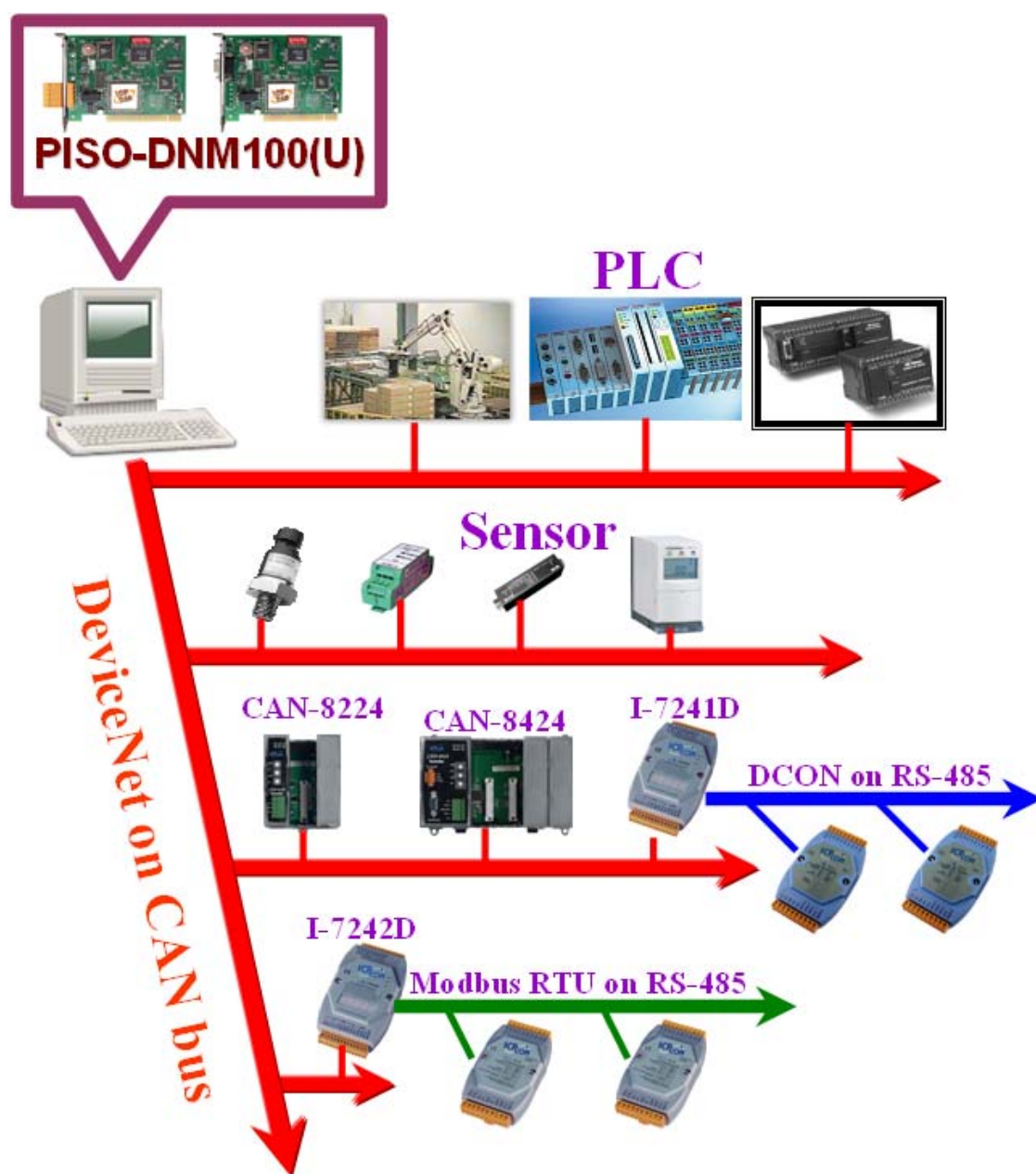


Figure 1.3 Application architecture

The DeviceNet protocol firmware provides the DeviceNet Master mechanism to communicate with slave devices by the Predefined Master/Slave Connection Set and UCMM Connection Set. In the DeviceNet communication protocol can be clarify as two forms: One is the Explicit Message and others are I/O Messages. Here, we only provide one explicit message connection and four I/O connections as depicted in Figure 1.4.

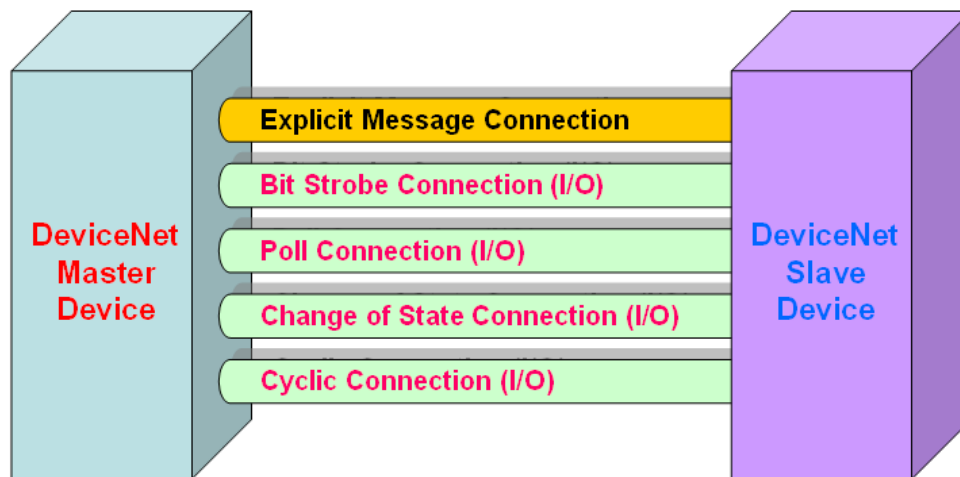


Figure 1.4 DeviceNet Messaging

The DeviceNet Communication Protocol is based on the concept of connections method. Master should create connections with slave devices based on the command of exchanging information and I/O data. To establish the master control mechanism, there are only four main steps to be followed. Figure 1.5 demonstrates the basic process for the DeviceNet master communication. The every step function is described in below:

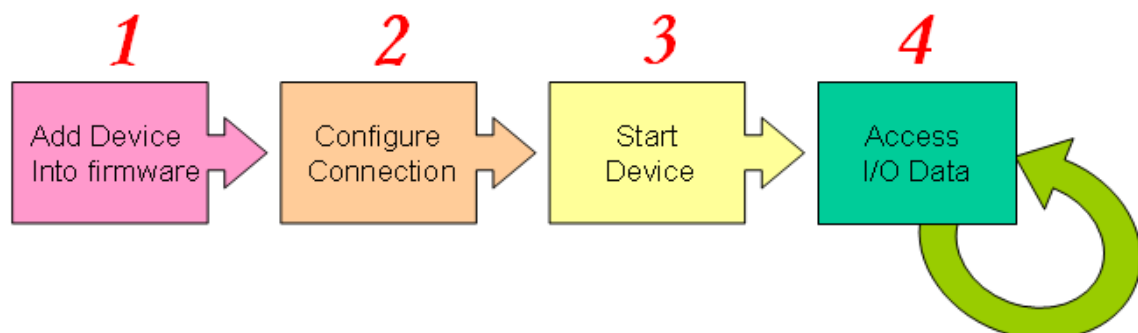


Figure 1.5 Four steps to establish connection

1. Add device into firmware

You should provide the slave device's MAC ID to add into firmware by using API function.

2. Configure connection

You can check the slave device's I/O connection type and the I/O data length. When configuring the I/O connection, you should provide these parameters.

3. Start Device

After configuring connections, users should start device by using API function. The master will communicate with the slave device.

4. Access I/O data

After communicating with slave devices, you can access the I/O data with corresponding read/write function.

After adding the device into the firmware, the master will wait for the I/O configuration information. Then users can create the I/O connections in the next step. Once I/O connections have been created and started, I/O data may be exchanged among devices in the DeviceNet network according to master device demand. Therefore, the master device can access I/O data of the slave devices by one of the four I/O connection methods. The API functions are not only easy to use but also providing a lot of the DeviceNet Master functions to retrieve and deliver the slave's I/O data. For more information, please refer to functions description and demo programs in section 4.

1.5 PISO-DNM100(U) Firmware Characteristics

The PISO-DNM100(U) is a high-performance DeviceNet master board. The firmware inside the board implements DeviceNet protocol automatically when the board is active. The firmware always listens to the bus and receives the message at the same time. It works as shown in Figure 1.6.

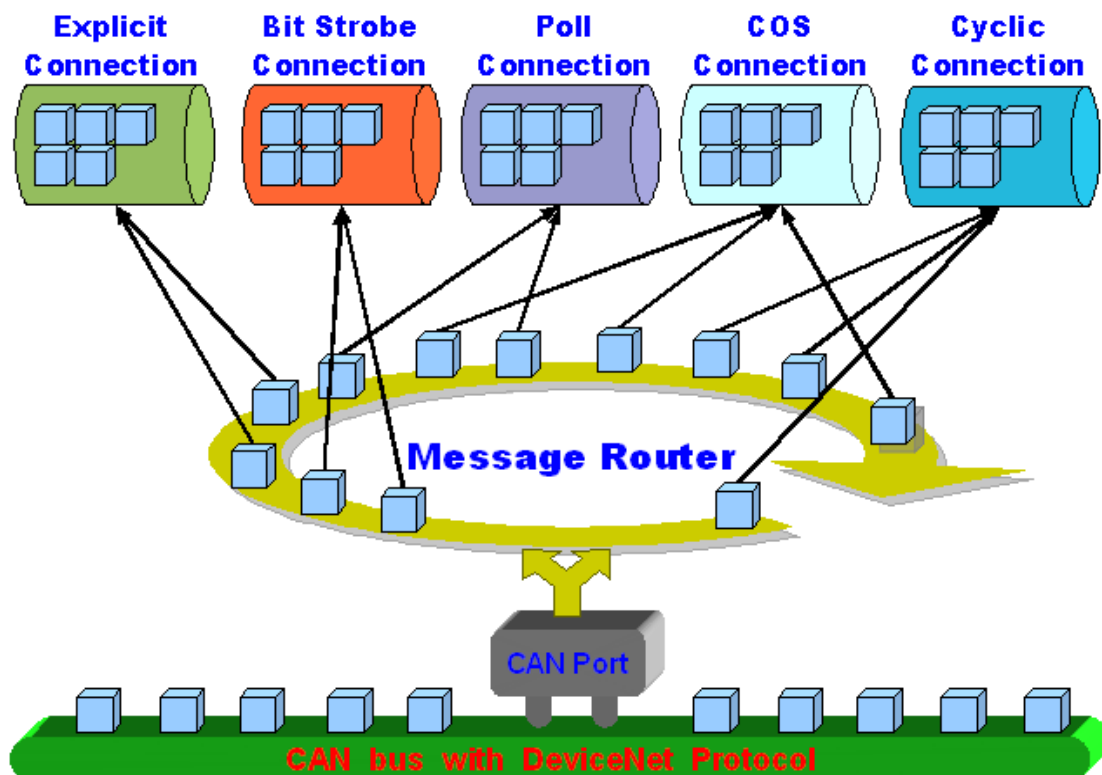


Figure 1.6 Message Router

The PISO-DNM100(U) firmware has a “ScanList” to store the remote slave devices information. After power off, the information still exists in the EEPROM. When the users turn on the PC next time, the “ScanList” will be loaded from EEPROM. The users can easily use the DLL functions to configure it, including adding devices or removing devices. It works as shown in Figure 1.7. There is more information about the library functions in chapter 4.

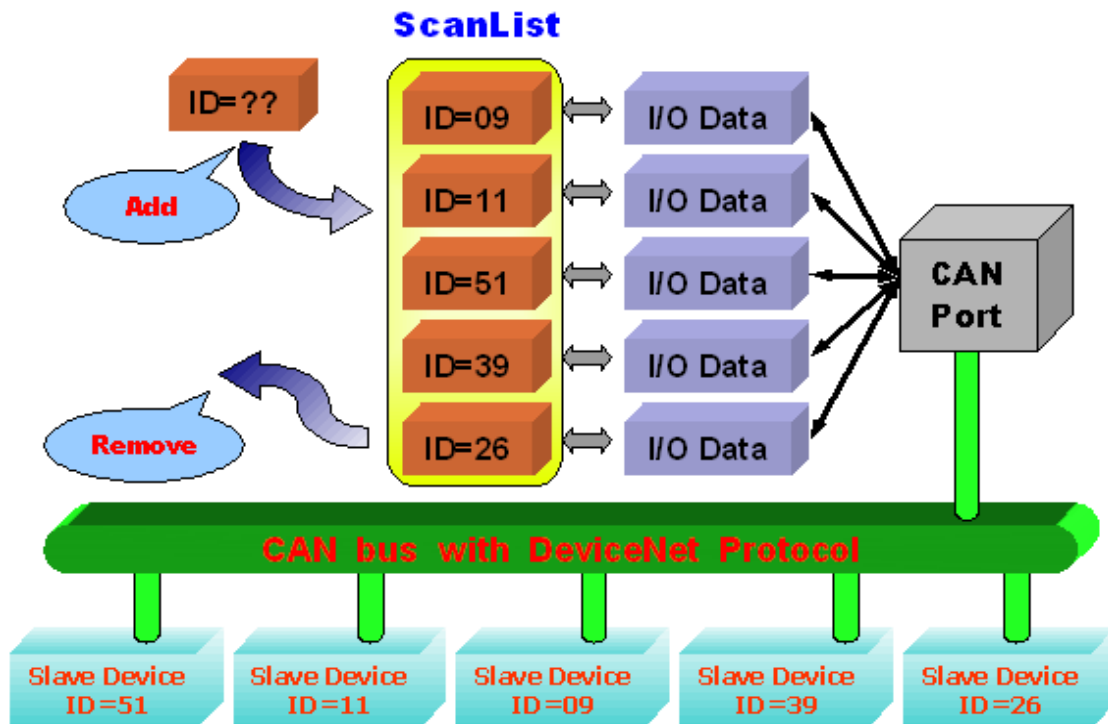


Figure 1.7 ScanList data structure

1.6 Features

Hardware Features

- PISO-DNM100-D/T.
 - * 33MHz 32bit 5V PCI bus (V2.1) plug and play technology.
- PISO-DNM100U-D/T
 - * Universal PCI card, supports both 5V and 3.3V PCI bus.
- Driver supported for Windows 98/ME/NT/2000/XP.
- 186 compatible CPU with DeviceNet firmware inside.
- 8K bytes DPRAM inside.
- One CAN communication port.
- Compatible with CAN specification 2.0 parts A and B.
- Jumper select 120Ω terminator resistor for each port.
- 2 indicating LED (one for green and another for red).
- Direct memory mapping to the CAN controllers.
- 2500Vrms photo-isolation protection on CAN bus.
- 3000Vrms galvanic DC/DC isolation on CAN side.

DeviceNet Firmware Features

- Programmable Master MAC ID.
- Programmable transfer-rate 125K, 250K, 500K.
- Each port support maximum nodes up to 64
- Support Group 2 Only Server functions
- Support UCMM functions
- Predefined Master-Slave Connection Set
- The maximum Fragment number is (Input/Output) up to 64
- Support I/O Operation Mode: Poll, Bit-Strobe and Change Of State/Cyclic
- Support Auto-Scan slave device function.
- Support on-line adding and removing devices.
- Support Auto-Reconnect when the connection is broken.

1.7 Specifications

- CAN controller: Phillips SJA1000T.
- CAN transceiver: Phillips 82C250.
- Signal support: CAN_H, CAN_L.
- CAN controller frequency :16 MHz
- Connector: 5-pin screw terminal connector or 9-pin D-sub male connector.
- 2500Vrms photo-isolation protection on CAN bus.
- 3000Vrms galvanic DC/DC isolation on CAN side.
- 186 compactable CPU
- 8K bytes DPRAM (1K bytes for system)
- 512 K bytes Flash memory (128K bytes for system)
- 512K bytes SRAM
- RTC (real time clock) inside
- 2K EEPROM (256 bytes for system)
- 31 bytes NVRAM
- Power requirements:
5V@400mA
- Environmental:
Operating temp: -25~75°C
Storage temp: -40~80°C
Humidity: 5~95% non-condensing
Dimensions: 127mm X 121mm

1.8 Block Diagram

The figure 1.8 shows the block diagram of the PISO-DNM100(U) board.

1. DPRAM (Dual Port RAM) :

The DPRAM is the memory buffer which provides the communication channel between PC and PISO-DNM100(U).

2. EEPROM :

The EEPROM stores the configuration information. After restarting the PC, the configuration data will be loaded form the EEPROM automatically.

3. Control CPU :

The CPU inside implementing the DeviceNet firmware.

4. CAN Controller :

The CAN controller is used for sending and receiving the CAN messages. There is photo isolation between CAN controller and CAN bus.

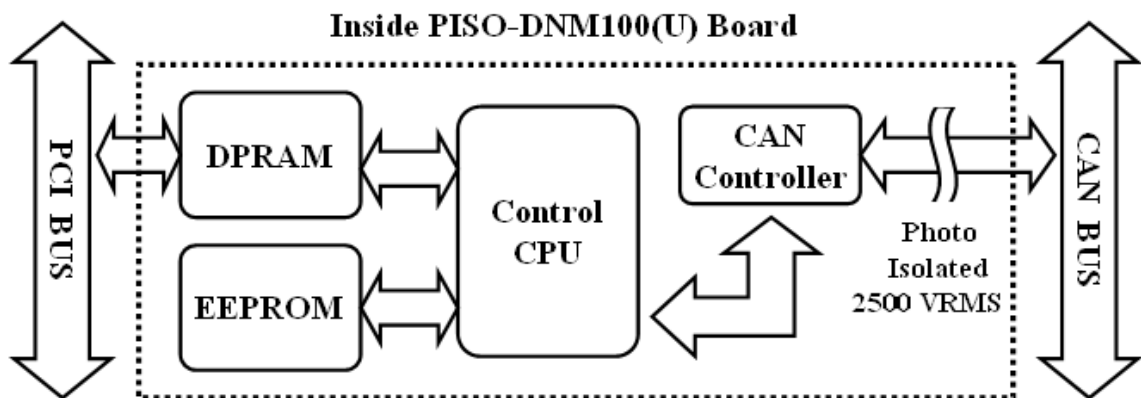


Figure 1.8 Block diagram of the PISO-DNM100(U)

1.9 Product Check List

In addition to this manual, the package includes the following items:

- ☐ PISO-DNM100(U) board;
- ☐ Software CD ROM;
- ☐ Quick Start manual;
- ☐ Release Note

It is recommended that users should read the release note first. All of the important information needed will be provided in the release note as follows:

- ☐ Where you can find the software driver, utility and demo programs.
- ☐ How to install software & utility.
- ☐ Where is the diagnostic program?
- ☐ FAQ's and answers.

Attention !

If any of these items are missing or damaged, please contact your local field agent. Keep aside the shipping materials and carton in case you want to ship or store the product in the future.

2. Hardware Configuration

This section will describe the hardware settings of the PISO-DNM100(U). This information includes the wire connection and terminal resistance configuration for the CAN network.

2.1 Board Layout

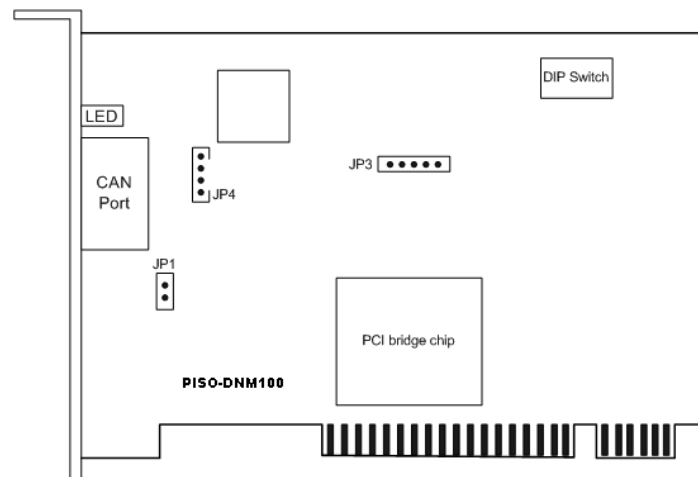


Figure2.1 PISO-DNM100 Board Layout

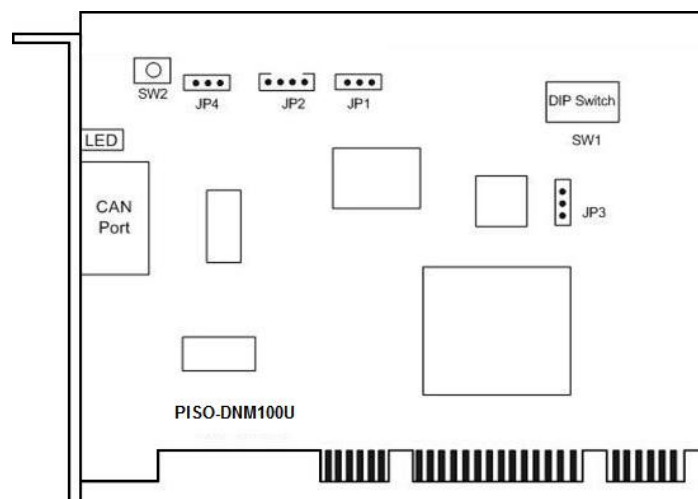


Figure 2.2 PISO-DNM100U Board Layout

Note: PISO-DNM100(U)-T layout is similar with PISO-DNM100(U)-D. The only difference is the position of CAN port connector. The positions of jumper or DIP switch are the same. Therefore, users can also refer to the PISO-DNM100(U)-D layout to configure the jumper or DIP switch if they use PISO-DNM100(U)-T.

2.2 Jumper Selection

The following table shows the definition of jumpers or DIP switch. Users need to refer to this table to configure the PISO-DNM100(U)- D/T hardware.

PISO-DNM100 :

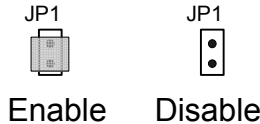
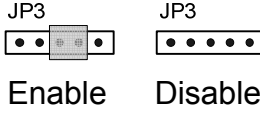

Jumper	Description	Status
JP1	CAN Port 120Ω terminal resistance.	
JP3	Reset pin for download error. If users want to update firmware but the process is fail, users can enable this jumper to reset the PISO-DNM100-D/T into download mode.	
JP4	None.	None
DIP switch	DIP switch is used to set the PISO-CM100 board No. Switch1 is for bit0, switch2 is for bit1 and so forth. For example, if the left-hand-side switch (switch 1) is ON, the board No. is set to 1. The range of board No. is from 0 to 15. Be careful that the board No. for each PISO-CM100-D/T, PISO-DNM100-D/T and PISO-CPM100-D/T must be unique.	 <p>This situation indicates the board No. 1.</p>

Table 2.1 Jumper or DIP switch selections for PISO-DNM100

PISO-DNM100U :


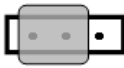
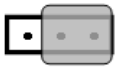
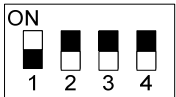
Jumper	Description	Status
JP1 JP2 JP3	None.	None.
SW2	Reset button for download error. If users want to update firmware but the process is fail, users can click this button to reset the PISO-DNM100(U) into download mode.	
JP4	CAN Port 120Ω terminal resistance.	<div style="display: flex; justify-content: space-around; align-items: center;"> <div style="text-align: center;">  Enable </div> <div style="text-align: center;">  Disable </div> </div>
DIP switch	<p>DIP switch is used to set the PISO-CM100(U) board No. Switch1 is for bit0, switch2 is for bit1 and so forth. For example, if the left-hand-side switch (switch 1) is ON, the board No. is set to 1. The range of board No. is from 0 to 15. Be careful that the board No. for each board</p> <ul style="list-style-type: none"> * PISO-CM100-D/T, * PISO-CM100U-D/T, * PISO-DNM100-D/T, * PISO-DNM100U-D/T * PISO-CPM100-D/T * PISO-CPM100-D/T <p>must be unique.</p>	<div style="text-align: center;"> <p>DIP switch</p>  </div> <p>This situation indicates the board No. 1.</p>

Table 2.2 Jumper or DIP switch selections for PISO-DNM100U

2.3 Connector Pin Assignment

The PISO-DNM100(U)-T is equipped with one **5-pin screw terminal connector** and the PISO-DNM100(U)-D is equipped with one **9-pin D-sub male connector** for wire connection of the CAN bus. The connector's pin assignment is specified as follows:

2.3.1 5-pin screw terminal connector

The 5-pin screw terminal connector for the CAN bus is shown in Figure 2.4 and the details for the pin assignment are presented in Table 2.2.

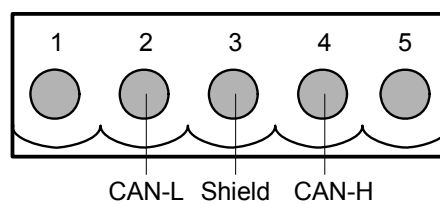


Figure2.4 5-pin screw terminal connector

Pin No.	Signal	Description
1	N/A	No use
2	CAN_H	CAN_H bus line (dominant high)
3	CAN_SHLD	Optional CAN Shield
4	CAN_L	CAN_L bus line (dominant low)
5	N/A	No use

Table 2.2: Pin assignment of 5-pin screw terminal connector

2.3.2 9-pin D-sub male connector

The 9-pin D-sub male connector of the CAN bus interface is shown in Figure 2.5 and the corresponding pin assignments are given in Table 2.3.

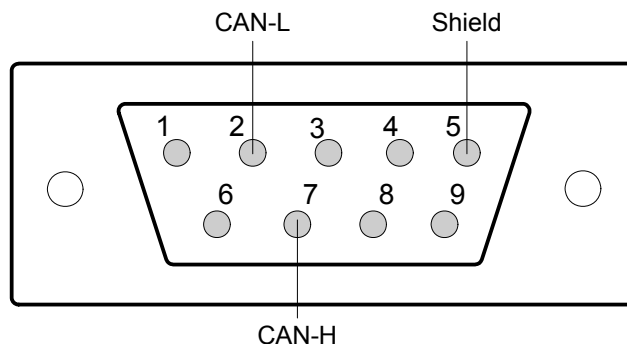


Figure2.5 9-pin D-sub male connector

Pin No.	Signal	Description
1	N/A	No use
2	CAN_L	CAN_L bus line (dominant low)
3	N/A	No use
4	N/A	No use
5	CAN_SHLD	Optional CAN Shield
6	N/A	No use
7	CAN_H	CAN_H bus line (dominant high)
8	N/A	No use
9	N/A	No use

Table 2.3 Pin assignment of the 9-pin D-sub male connector

2.3.3 Wire connection

In order to minimize the reflection effects on the CAN bus line, the CAN bus line has to be terminated at both ends by two terminal resistances as in the following figure. According to the ISO 11898-2 spec, each terminal resistance is 120Ω (or between $108\Omega\sim132\Omega$). The length related resistance should have $70\text{ m}\Omega/\text{m}$. Users should check the resistances of the CAN bus, before they install a new CAN network.

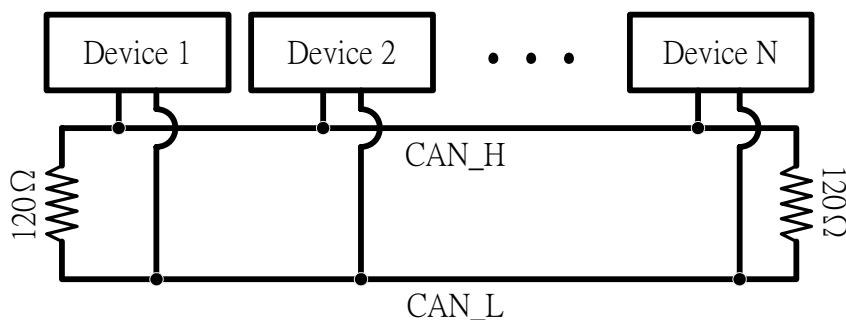


Figure 2.4 CAN bus network topology

Moreover, to minimize the voltage drop over long distances, the terminal resistance should be higher than the value defined in the ISO 11898-2. The following table can be used as a good reference.

Bus Length (meter)	Bus Cable Parameters		Terminal Resistance (Ω)
	Length Related Resistance ($\text{m}\Omega/\text{m}$)	Cross Section (Type)	
0~40	70	0.25(23AWG)~ 0.34 mm^2 (22AWG)	124 (0.1%)
40~300	< 60	0.34(22AWG)~ 0.6 mm^2 (20AWG)	127 (0.1%)
300~600	< 40	0.5~0.6 mm^2 (20AWG)	150~300
600~1K	< 20	0.75~0.8 mm^2 (18AWG)	150~300

Table 2.4 Relationship between cable characteristics and terminal resistance

2.4 Indicator LED

2.4.1 Green LED

The [Green] LED indicates the firmware status in the PISO-DNM100(U). There are 3 situations in [Green] LED.

(1). LED off:

This indicates that there are some errors on the bus or in the firmware. The DeviceNet firmware is not running.

(2). LED twinkle:

This indicates that the CAN bus works fine. But there is no any slave devices configuration in the EEPROM of the PISO-DNM100(U). The DeviceNet firmware is waiting for configuration.

(3). LED on:

This indicates that the DeviceNet firmware is running. The PISO-DNM100(U) is communicating with the slave devices.

2.4.2 Red LED

The [Red] LED means Network Status. It indicates that there are errors on the bus or there is any slave device's MAC ID collides with the PISO-DNM100(U)'s MAC ID. There are two situations in [Red] LED.

(1). LED off:

This indicates that there is no error on the bus and about the MAC ID.

(2). LED twinkle:

This indicates that there are errors on the bus which maybe the situations as shown bellow:

- (a) The CAN connector doesn't connect to the slave devices.
- (b) The power of the slave devices is off.
- (c) The MAC ID collision between master and slave devices is occurring.

2.5 Hardware Installation

When users want to use PISO-DNM100(U)-D/T, the hardware installation needs to be finished as following steps.

1. Shutdown your personal computer.
2. Configure the DIP switch and JP1 of your PISO-DNM100-D/T for board No. and terminal resistance. More detail information could be found on the figure 2.1 and table 2.1. For the PISO-DNM100U-D/T, configure the DIP switch and JP4 of your PISO-DNM100U-D/T for board No. and terminal resistance. More detail information could be found on the figure 2.2 and table 2.2.
3. Check JP3 status of PISO-DNM100-D/T. If necessary, enable it. For the PISO-DNM100U-D/T, you can visit the next step.
4. Find an empty PCI slot for your PISO-DNM100(U)-D/T on the mother board of the personal computer. Plug the configured PISO-DNM100(U)-D/T into this empty PCI slot. See figure 2.5.
5. Plug your CAN bus cable(s) into the 5-pin screw terminal connector or the 9-pin D-sub connector.

When the steps described above is completed, turn on the personal computer.

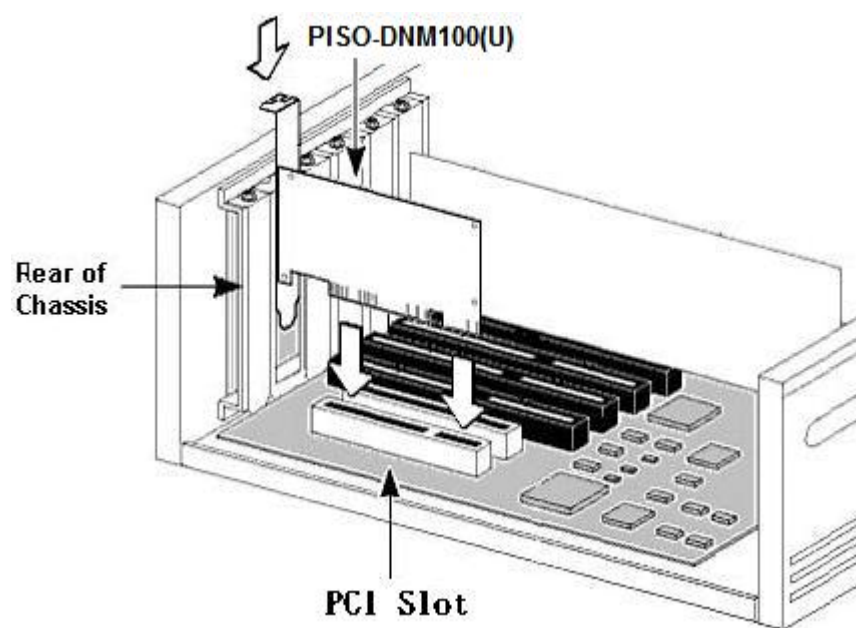


Figure 2.5 PISO-DNM100(U) installation

3. Driver Installation and Software Application

The DeviceNet DLL driver (DNM100.dll) collection of function calls for the PISO-DNM100(U) cards used in Windows 98/Me/NT/2000/XP systems. The application structure is presented in the following figure. The user's DeviceNet application programs can be developed by the following designated tools: VB, Delphi and Borland C++ Builder...etc. In these tools, the application program can call the DNM100.DLL driver to implement DeviceNet network application. And then the DeviceNet DLL driver will throughout the CM100.dll into the KP_CM100.sys and windrvr6.sys to access the hardware system, as shown in the following Figure.

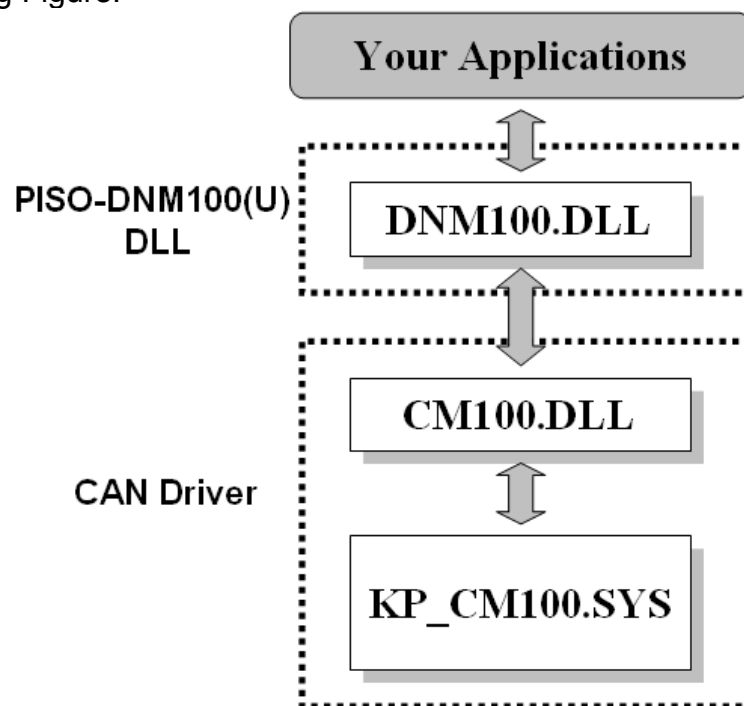


Figure 3.1 Software architecture in the Windows system

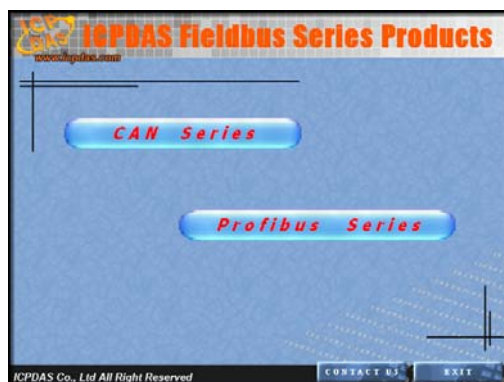
In the following sub-section, we show some flow diagrams to describe how to apply the DeviceNet protocol (DNM100.DLL) to build a master device. Section 3.2 ~ 3.10 show the flow diagram for users to understand easily. Note that users need to follow the operation principle of the DeviceNet protocol correctly and easily to communicate with the remote nodes by these connection methods.

3.1 Driver Installation of the PISO-DNM100(U)

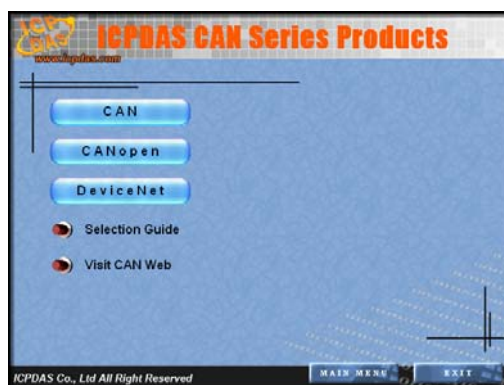
The software Installation for DeviceNet application is demonstrated as the following descriptions. After finishing the procedure, the driver, demos, manual and Utility can be in your PC. For the advance application, users can refer to the basic demo programs to develop the customized DeviceNet master application.

The driver of PISO-DNM100(U) can be used in 98/Me/NT/2000/XP Windows environments. For these Windows operation systems, the recommended installation procedure is given as follows:

Step 1: Insert the companion CD into the CD-ROM driver and wait a few seconds until the installation program starts automatically. If it cannot be started automatically for some reason, please double-click the file **ICPDAS.EXE** on this CD. The screenshot likes the following picture. Please click “CAN Series” item.



Step 2: After changing to the following picture, please click the “DeviceNet” item.



Step 3: When the window is changing to the picture below, please move the mouse cursor on the “Master” item.



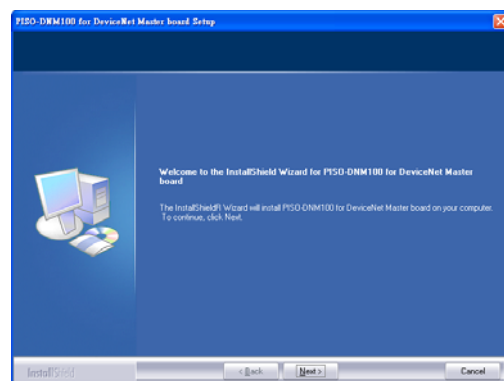
Step 4: The DeviceNet master products will be shown in the window.



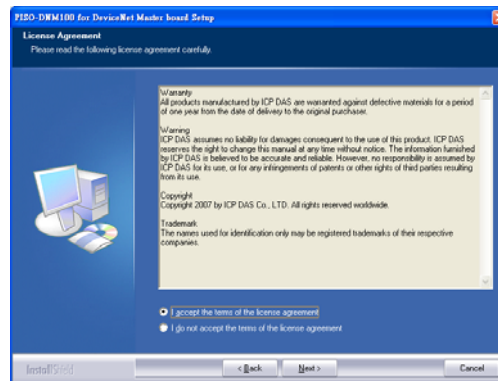
Step 5: Click “install Toolkit” to install the driver of the PISO-DNM100(U) board.

Step 6: After finishing the step 5, the users will see the setup file in the folder “PISO-DNM100_V30.exe”. Please double-click it to run the setup.

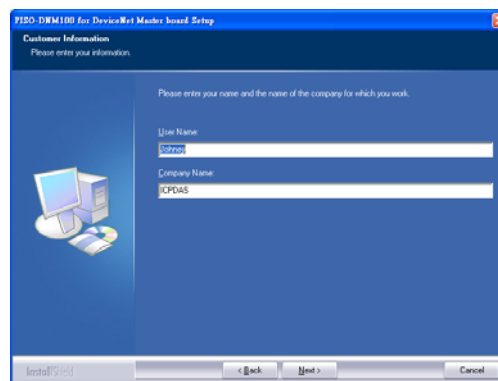
Step 7: This first setup screen shoot is shown as follows. Please press “Next” button to continue the process.



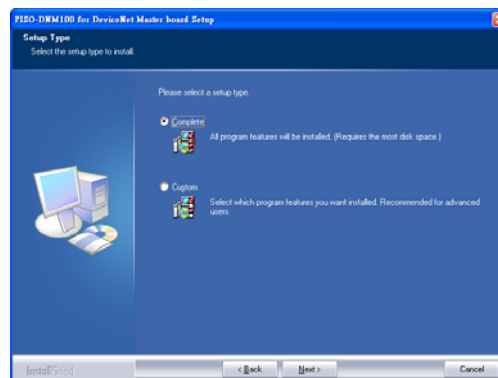
Step 8: Press “Next” button. The screen shoot is shown below. After reading the license, the users can accept it or not. If the users accept it, please select “I accept...” and press “Next” button.



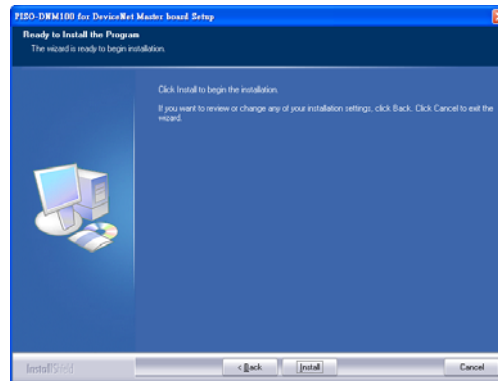
Step 9: After accepting the license, the next screen shoot is shown as follows. Users can edit your name and company name. After editing the information, please press “Next” button.



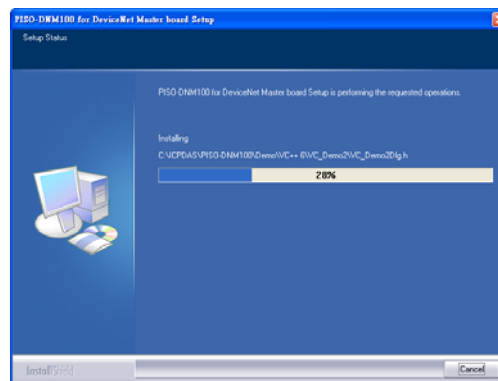
Step 10: After editing the information, the next screen shoot is shown as follows. Please select “Complete” item and press “Next” button.



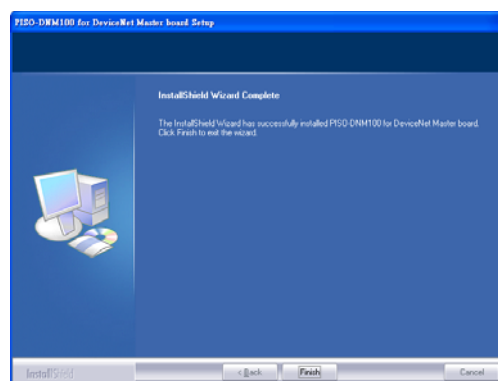
Step 11: The next screen shoot is shown as follows. Please press “Install” button. The setup process will start.



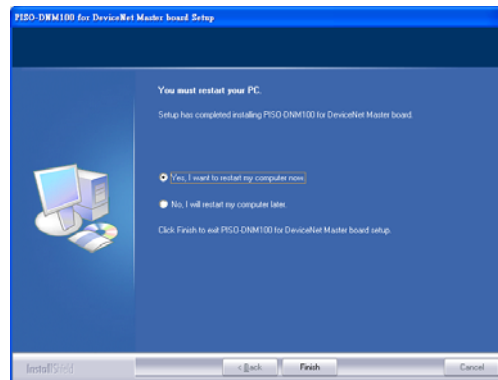
Step 12: The setup process is running. The screen shoot is shown below.



Step 13: Wait for the setup process finishing. The next screen shoot is shown below. After finishing the process, please press “Finish” button.



Step 14: The next screen shoot is shown as follows. Please restart your PC.



Then the setup software would copy the related material to the indicated directory and register the driver on your computer. The driver target directory is different according to the different systems as follows.

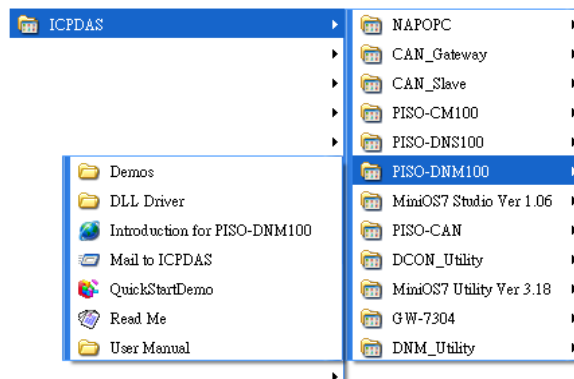
Windows NT/2000 – **WINNT\SYSTEM32\DRIVERS**

Windows 98/Me/XP – **WINDOWS\SYSTEM32\DRIVERS**

The other data and resource is copied to the following directory:

C:\ICPDAS\PISO-DNM100

The program files picture is shown as follow.



Note : DeviceNet Master Utility is a useful tool for users to configure and test the DeviceNet slave devices. You can find the software in the path of /devicenet/Master/DNM_Utility/ in the Fieldbus_CD or from ftp://ftp.icpdas.com/pub/cd/fieldbus_cd/devicenet/master/DNM_Utility. After installing the software, the utility is installed in the path below.
C:\ICPDAS\DNM_Utility\DNM_Utility.exe
Please refer to the manual of utility to know the detail.

3.2 Flow Diagram for Searching Devices

Before developing the DeviceNet applications, users should diagnose the connection between the slave devices. First, the users can search the slave devices in the network by using the searching functions. If the connection between the master with other slave devices is fine, the users can find the information of the corresponding slave devices. When the users have no idea to communicate with the slave devices, users can follow these steps shown in figure 3.2. The following functions can help users to get the DeviceNet information of the slave devices. The users can find out the problem of the slave devices by using these functions. The detail information about those functions is in the next chapter.

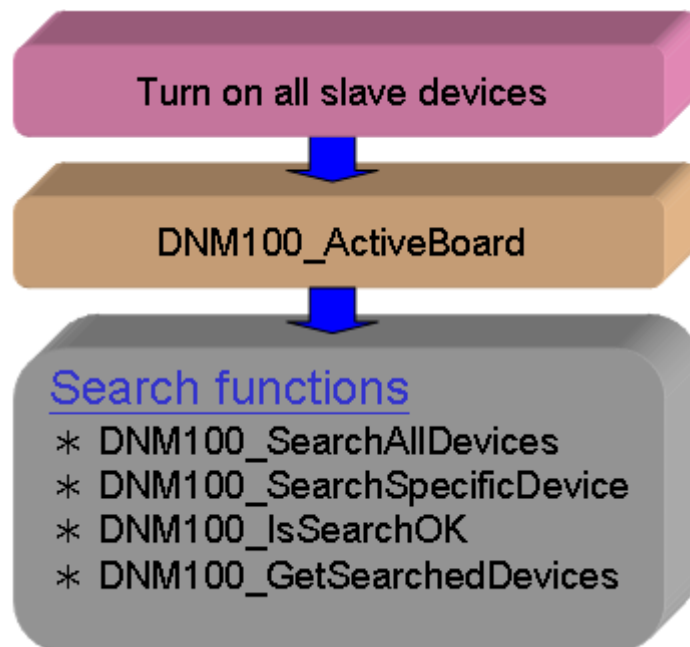


Figure 3.2 Searching Diagram

3.3 Flow Diagram for Slave Configuration

After getting the DeviceNet I/O information of the slave devices, users should save the parameters into the EEPROM in PISO-DNM100(U). The EEPROM will store the configuration data. The firmware in PISO-DNM100(U) will load the previous configuration from the EEPROM in the next boot-up. When the devices in the DeviceNet network are changed, the users must set the configuration data to fit the application. The configuration diagram is shown in Figure 3.3. There is more information about those functions in the next chapter.

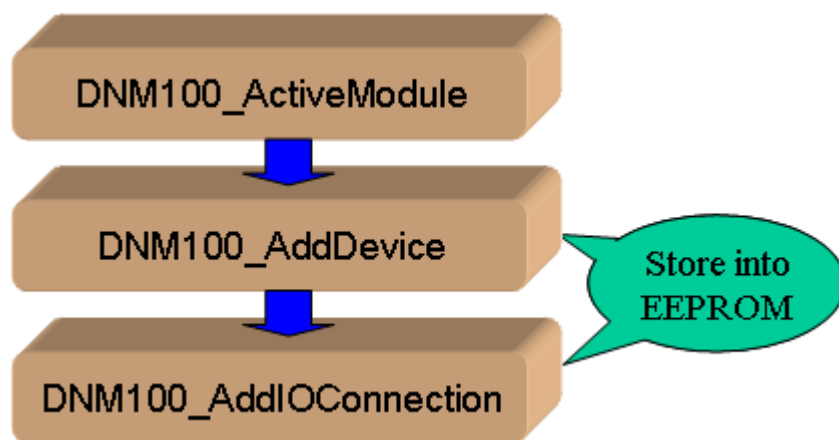


Figure 3.3 Slave Configuration Diagram

3.4 Flow Diagram for On-line Adding/Removing Device

The PISO-DNM100(U) provides the on-line adding/removing slave device functions. The users need not to break the communication between original slaves device when adding or removing the slave devices. The users can follow the steps to achieve this function. The steps are shown in Figure 3.6 and Figure 3.7.

1. On-line Adding Devices :

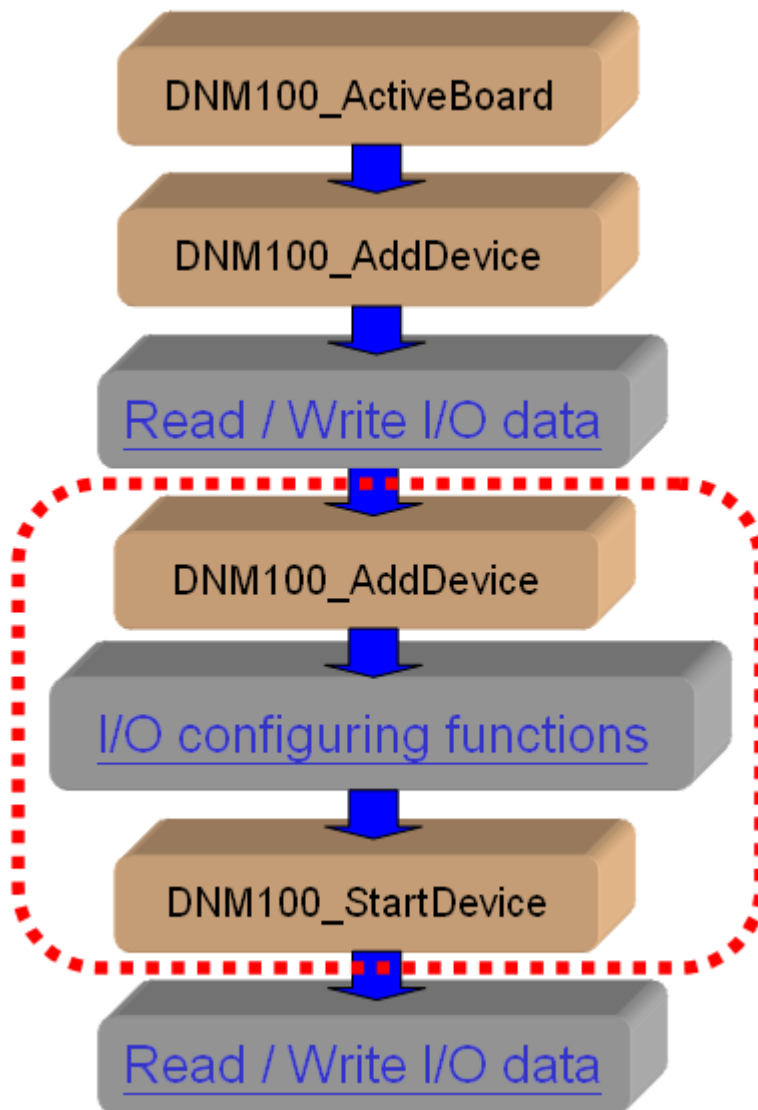


Figure 3.6 On-line Add Device Diagram

2. On-line Removing Devices :

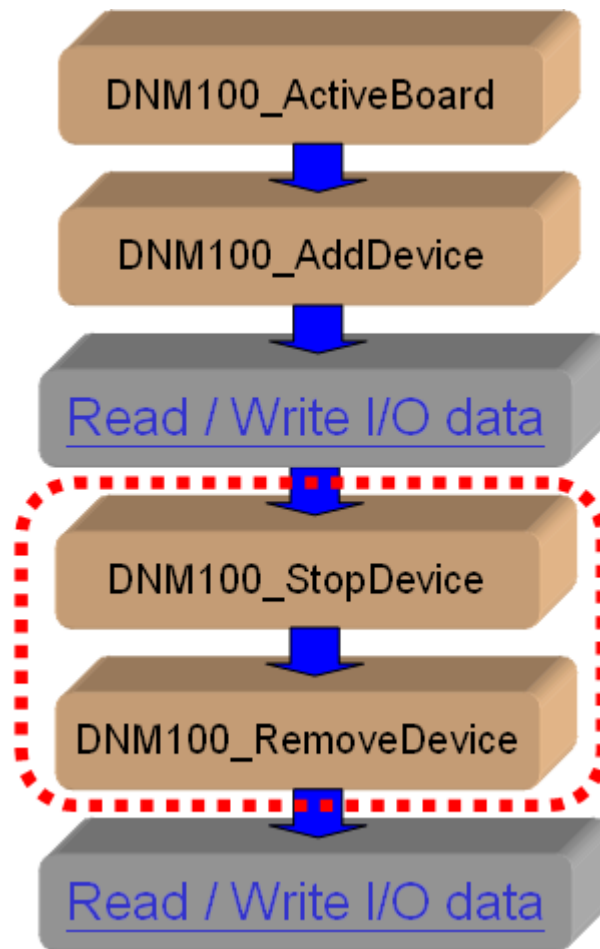


Figure 3.7 On-line Remove Device Diagram

3.5 Flow Diagram for “SetAttribute” and “GetAttribute”

The users can set or get DeviceNet device's property via DeviceNet network. The PISO-DNM100(U) provides these functions to set or get the properties of the remote devices easily. The steps are shown in Figure 3.8.

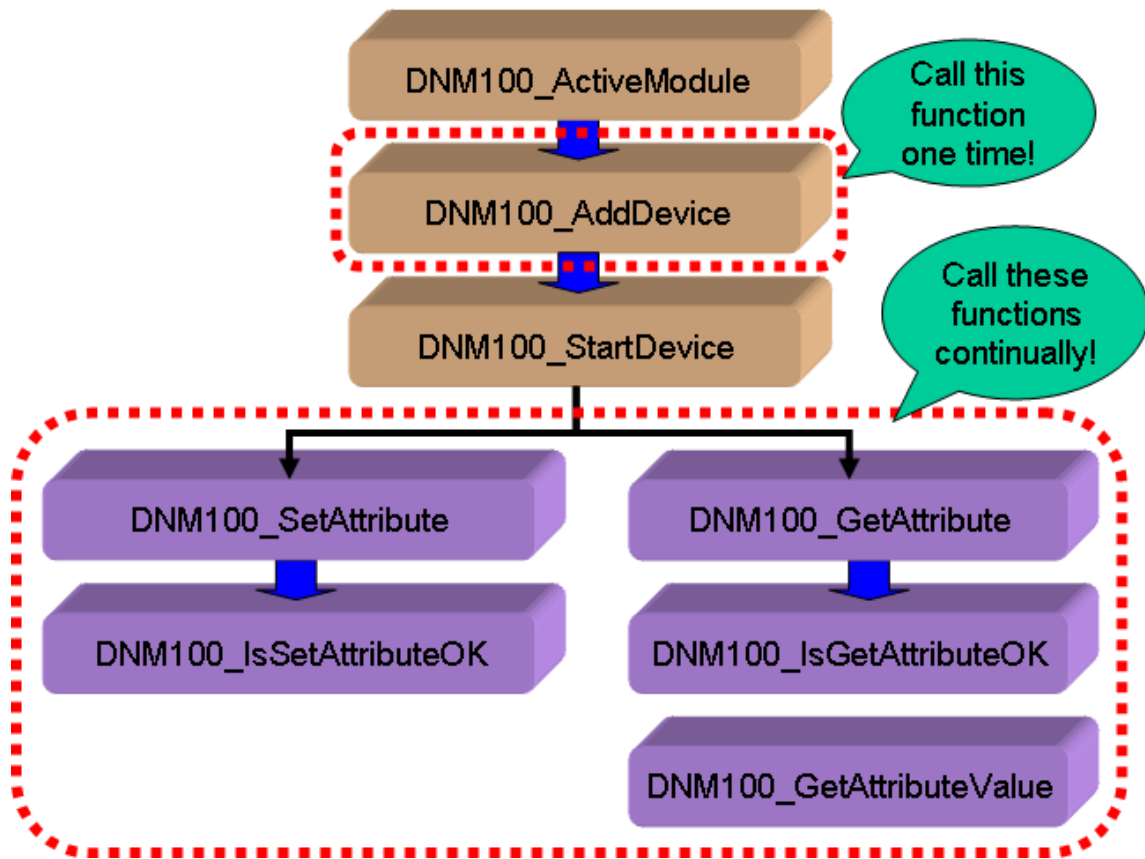


Figure 3.8 “SetAttribute” and “GetAttribute” Diagram

3.6 Flow Diagram for I/O Connection

The users can read or write device's I/O data via the DeviceNet I/O connections like Poll, Strobe, COS and Cyclic connection. There are four important steps to read and write the I/O data easily. Firstly, the users should know the device's I/O input length (in Byte) and output length (in Byte). Secondly, the users should set these two parameters by calling DNM100_AddIOConnection. Thirdly, the users can set the initial output value by calling DNM100_WriteOutputData before starting the specific slave device. If the users do not initialize the output value, the firmware default output value is 0. Fourthly, the users can start communicating with device to read or write I/O data. If the specific slave device doesn't have any output channel, the firmware will start communicating with the device automatically. The Figure 3.9 shows the main steps to achieve this function. There are more functions described in chapter 4.

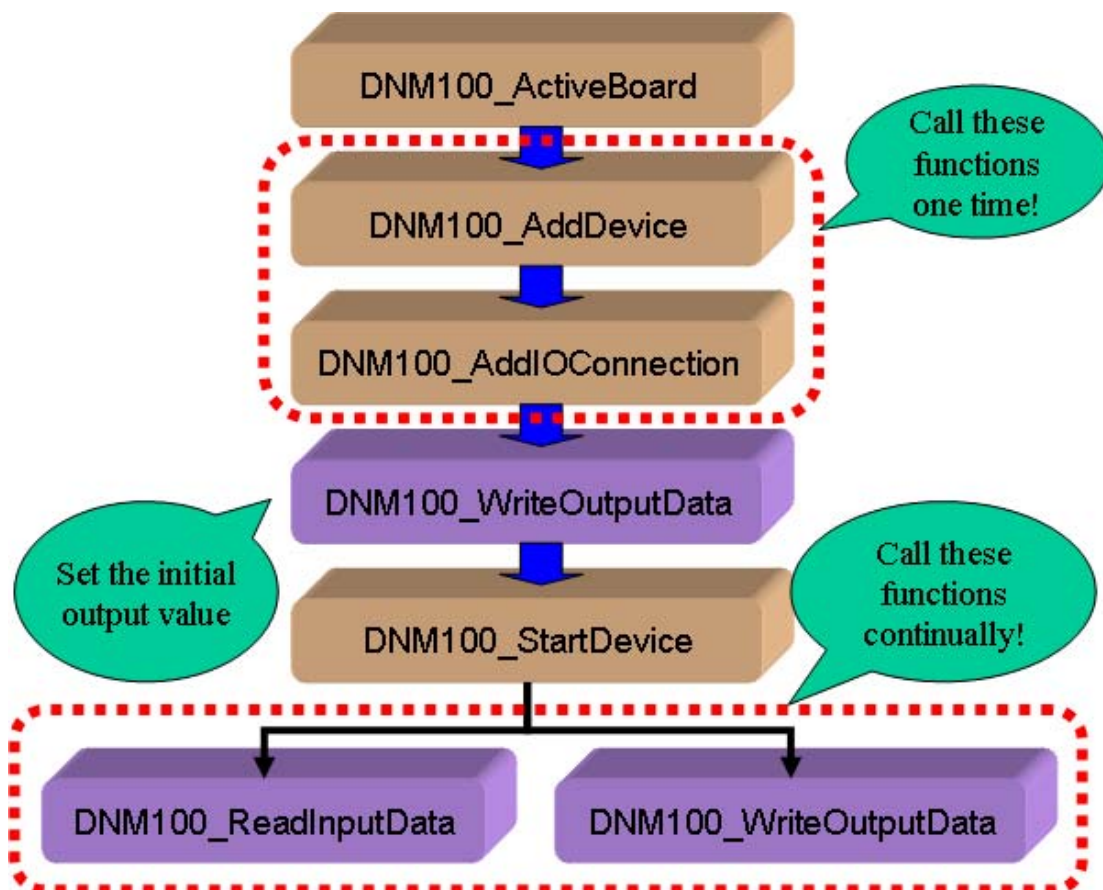


Figure 3.9 I/O Connection Diagram

Note: The Strobe connection doesn't support the output channel. The users can not use the DNM100_WriteOutputData with Strobe connection.

3.7 Input and Output I/O Data Area (Advanced Option)

Here exist two memory areas, “Remote Input Area” and “Remote Output Area”. The input data of all DeviceNet slaves would be stored in the “Remote Input Area”, and the output data of them would be in the “Remote Output Area”. Please refer to the Figure 3.10.

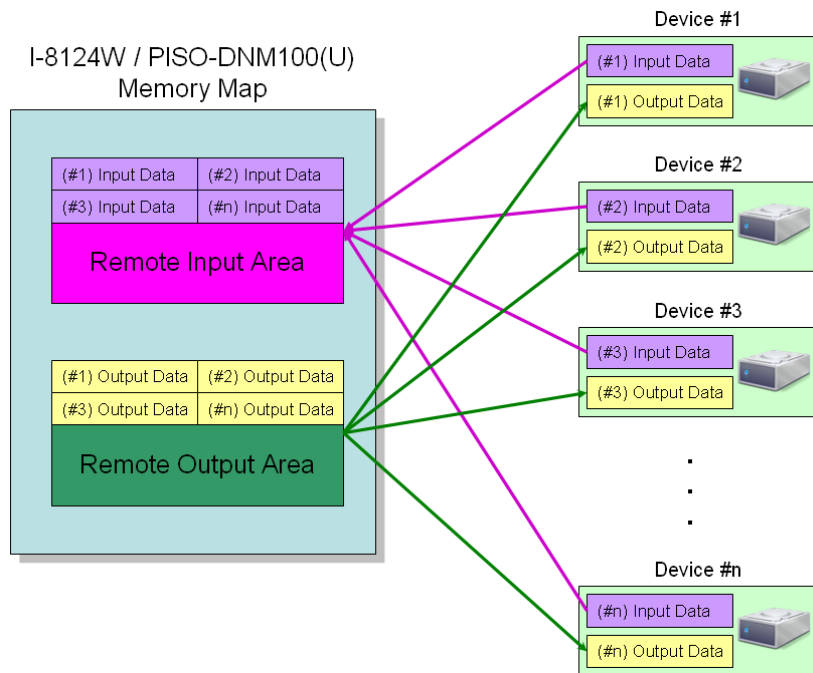


Figure 3.10 The Memory Mapping of the PISO-DNM100(U)

Users can read a bulk data from “Remote Input Area” in the PISO-DNM100(U). This bulk data contains multiple devices’ input statuses. If one of the input status of the remote DeviceNet slave changes, the corresponding data located in the “Remote Input Area” would change immediately. Oppositely, the “Remote Output Area” contains multiple devices’ output data. Users may change the output value of a certain device by changing the corresponding data located in the “Remote Output Area”.

There is another important thing. Users need to know what the arrangement of those data. The data of the slave with the smallest DeviceNet MAC ID would be located in the most front of the Remote Input/Output Area. The data of the slave with the following MAC ID would be located in the following section, and so on. The data of the slave with the largest MAC ID would be located in the last section of the Remote Input/Output Area. Here shows three examples about the arrangement rule of the PISO-DNM100(U).

Example 1 :

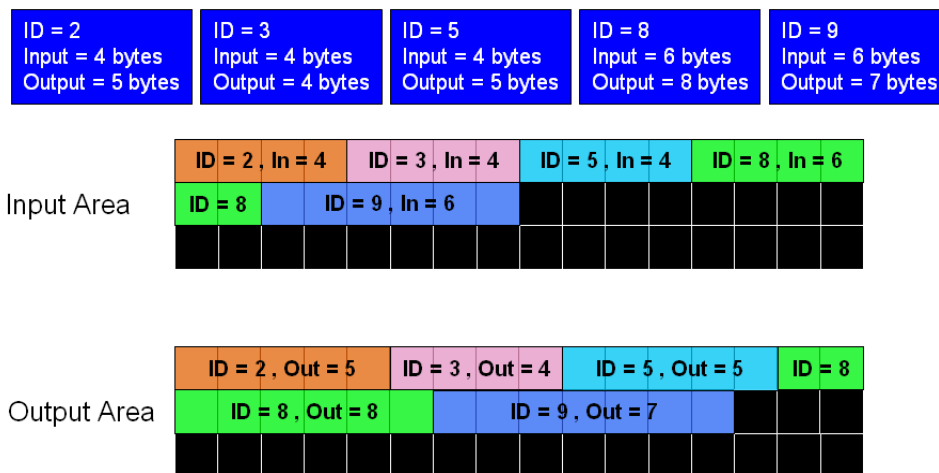


Figure 3.11 The example of the PISO-DNM100(U) memory mapping

Example 2 :

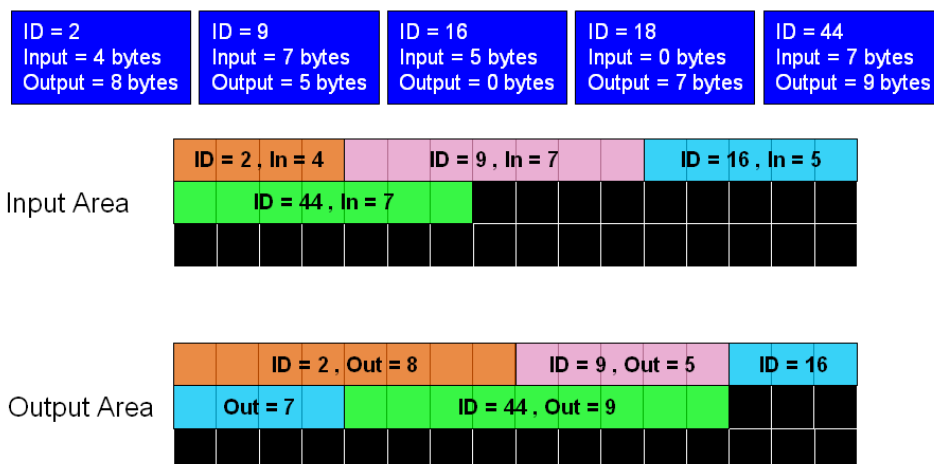


Figure 3.12 The example of the PISO-DNM100(U) memory mapping

Example 3 :

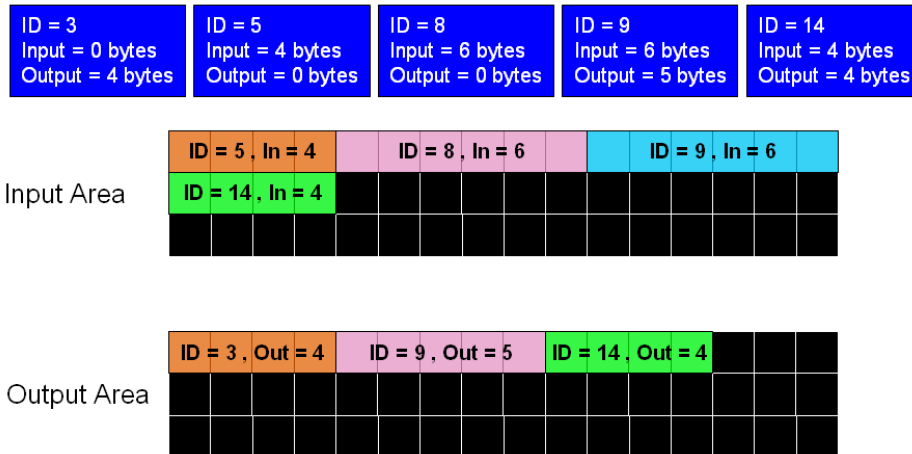


Figure 3.13 The example of the PISO-DNM100(U) memory mapping

User can read data from the “Remote Input Area” or write data to the “Remote Output Area”. There are three functions to access these two areas.

1.DNM100_ReadInputArea

Call this function to get a bulk data from the “Remote Input Area”. Please refer to the section 4.3.41 for more information.

2.DNM100_WriteOutputArea

Call this function to set a bulk data to the “Remote Output Area”. Please refer to the section 4.3.42 for more information.

3.DNM100_ReadbackOutputArea

Call this function to get a bulk data from “Remote Output Area”. Please refer to the section 4.3.43 for more information.

Note:

If users add/remove any slaves’ information into/from the PISO-DNM100(U), they need to reset firmware to update the modification of the data arrangement of the “Remote Input Area” and “Remote Output Area”. In other word, if users have called these functions below, they need to call DNM100_ResetFirmware to make the modification active.

1. DNM100_AddDevice
2. DNM100_RemoveDevice
3. DNM100_AddIOConnection
4. DNM100_RemoveIOConnection

4. Function description

All the functions of the PISO-DNM100(U) can be separated into five groups. The idea is shown Figure 4.1. There is more detail description in CH 4.1.

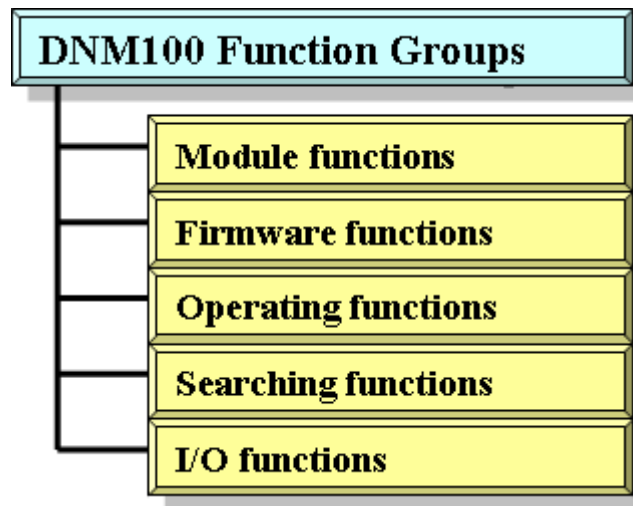


Figure 4.1 Five Function Groups

[Board Functions]

These functions in this group help users to find DNM100 boards or get board's information. The users can use these functions to configure or manage the boards in the PC.

[Firmware Functions]

These functions in this group help users to operate the firmware or get the status of the firmware inside the PISO-DNM100(U).

[Operating Functions]

These operating functions are the important operation of the DeviceNet master. They help users to configure the whole network.

[Searching Functions]

These searching functions can help user to debug the network, including the wire connection, the slave device's setting, and etc. When building the DeviceNet network, the user can use these functions to make sure that the network or the slave devices are fine.

[I/O Functions]

These functions help user to read or to write the I/O data from or to the

remote slave devices.

4.1 DLL Function Definition and Description

All the functions provided in the DNM100.DLL are listed in the following table and detail information for every function is presented in the next sub-section. However, in order to make the descriptions more simply and clear, the attributes for the both the input and output parameter functions are given as **[input]** and **[output]** respectively, as shown in the following table.

Keyword	Set parameter by user before calling this function?	Get the data from this parameter after calling this function?
[input]	Yes	No
[output]	No	Yes

Table 4.1.1 Functions Table (Board Functions) 1/1

No.	Function Name	Description
1	DNM100_GetBoardInf	Get the driver information of the PISO-DNM100(U)
2	DNM100_TotalDNM100Board	Get total PISO-DNM100(U) boards in the PC
2	DNM100_ActiveBoard	Enable the driver of the PISO-DNM100(U)
3	DNM100_CloseBoard	Close driver of the PISO-DNM100(U)
4	DNM100_GetDLLVersion	Get the DLL version of the DNM100.DLL

Table 4.1.2 Functions Table (Firmware Functions) 1/1

No.	Function Name	Description
1	DNM100_GetFirmwareVersion	Get the version of the firmware inside the PISO-DNM100(U) board
2	DNM100_ResetFirmware	Reset the firmware in the PISO-DNM100(U) board

Table 4.1.3 Functions Table (Operating Functions) 1/2

No.	Function Name	Description
1	DNM100_SetMasterMACID	Set the MAC ID of the PISO-DNM100(U) board (DeviceNet Master's MAC ID)
2	DNM100_GetMasterMACID	Get the MAC ID of the PISO-DNM100(U) board (DeviceNet Master's MAC ID)
3	DNM100_GetBaudRate	Get the baud rate of the CAN bus
4	DNM100_SetBaudRate	Set the baud rate of the CAN bus
5	DNM100_GetMasterStatus	Get the status of the PISO-DNM100(U) board (DeviceNet Master's status)
6	DNM100_GetSlaveStatus	Get the slave device's status.
7	DNM100_StartDevice	PISO-DNM100(U) will start to communicate with the specific slave device
8	DNM100_StopDevice	PISO-DNM100(U) will stop to communicate with the specific slave device
9	DNM100_StartAllDevice	PISO-DNM100(U) will start to communicate with all slave devices
10	DNM100_StopAllDevice	PISO-DNM100(U) will stop to communicate with all slave devices
11	DNM100_AddDevice	Add the specific slave device's information into the PISO-DNM100(U) board (DeviceNet Master)
12	DNM100_RemoveDevice	Remove the specific slave device's information from the PISO-DNM100(U) board (DeviceNet Master)
13	DNM100_AddIOConnection	Add I/O information of the specific slave device into the PISO-DNM100(U) board (DeviceNet Master)
14	DNM100_RemoveIOConnection	Remove specific slave device's I/O information from the PISO-DNM100(U) board (DeviceNet Master)

Table 4.1.4 Functions Table (Operating Functions) 2/2

No.	Function Name	Description
16	DNM100_GetAttribute	Send the get attribute command to the slave device.
17	DNM100_IsGetAttributeOK	Check whether the slave has replied for the getting command or not.
18	DNM100_GetAttributeValue	Get the attribute value of the DNM100_GetAttribute
19	DNM100_SetAttribute	Send the set attribute command to the slave device.
20	DNM100_IsSetAttributeOK	Check whether the slave has replied for the setting command or not.
21	DNM100_GetDeviceInfoFromScanList	Get specific slave device's I/O information from the Scan List within the PISO-DNM100(U) board.
22	DNM100_GetScanList	Get the I/O information of all slave devices from the Scan List within the PISO-DNM100(U) board.
23	DNM100_ImportEEPROM	Write the I/O information of all slave devices into the EEPROM within the PISO-DNM100(U) board.
24	DNM100_ClearAllConfig	Clear all configurations in the EEPROM within the PISO-DNM100(U) board.

Table 4.1.5 Functions Table (Searching Functions) 1/1

No.	Function Name	Description
1	DNM100_SearchAllDevices	PISO-DNM100(U) will search the DeviceNet network to find out the I/O information of all slave devices.
2	DNM100_SearchSpecificDevice	PISO-DNM100(U) will search the DeviceNet network to find out the I/O information of specific slave devices.
3	DNM100_IsSearchOK	Check whether the PISO-DNM100(U) has searched completely or not.
4	DNM100_GetSearchedDevices	Get the result of the searching command and retrieve the slave's I/O information.

Table 4.1.6 Functions Table (I/O Functions) 1/1

No.	Function Name	Description
1	DNM100_ReadInputData	Read the input data via I/O connection like Poll, Strobe, COS, Cyclic.
2	DNM100_WriteOutputData	Write the output data via I/O connection like Poll, COS, Cyclic. The Strobe doesn't support this operation.

4.2 Function Return Code

Table 4.2.1 Interpretation of the return code (Hardware Error) 1/1

Return Code	Error ID	Comment
0	DNM100_NoError	No error
10001	DNM100_DriverError	Kernel driver is not opened.
10002	DNM100_ActiveBoardError	This board can not be activated.
10003	DNM100_BoardNumberError	The Board number exceeds the total board numbers.
10004	DNM100_PortNumberError	The Port number is not correct.
10007	DNM100_InitError	The PISO-DNM100(U) replies error.
10021	DNM100_SoftBufferIsEmpty	No CAN messages in the buffer.
10022	DNM100_SoftBufferIsFull	The software buffer is overflow.
10023	DNM100_TimeOut	The PISO-DNM100(U) has no response.
10024	DNM100_SetCyclicMsgFailure	The cyclic messages are over 5 counts. This is special function for CAN.
10025	DNM100_DpramOverRange	The command length is over 512 bytes.
10026	DNM100_NoDpramCmd	There is no command in DPRAM.
10027	DNM100_ModeError	This board can't be changed to firmware mode.
10030	DNM100_NoFileInside	There is no firmware in PISO-DNM100(U).
10031	DNM100_DownloadFailure	The download firmware process is failure.
10032	DNM100_EEPROMDamage	The EEPROM is out of order.
10033	DNM100_NotEnoughSpace	The firmware is too large to put it into the PISO-DNM100(U)-D/T
10034	DNM100_StillDownloading	The firmware is downloading.
10035	DNM100_BoardModeError	The firmware mode is error.
10036	DNM100_CardTypeError	The firmware is not for the PISO-DNM100(U).

Table 4.2.2 Interpretation of the return code (General Error) 1/1

Return Code	Error ID	Comment
5000	DNMXS_UnKnowError	The DeviceNet has some unknown errors.
1000	DNMXS_BoardNotActive	The PISO-DNM100(U) has not been activated.
1001	DNMXS_OnlineError	The master MAC ID collides with other slave device in the DeviceNet network.
1002	DNMXS_CANBusError	The CAN port can't send message. Please check the baud rate or the port of the CAN bus.
1003	DNMXS_Booting	The PISO-DNM100(U) is still booting.
1050	DNMXS_MACIDError	The MAC ID is exceed the range(0 ~ 63)
1051	DNMXS_BaudRateError	The baud rate is exceed the range(0 ~ 2)
1052	DNMXS_ConnectionTypeError	The connection type is exceed the range (0 ~ 4)
1053	DNMXS_DuplicMasterMACID	The MAC ID is the same with the master's ID.
1054	DNMXS_EEPROMError	The EEPROM is out of order.
1055	DNMXS_NowScanning	The PISO-DNM100(U) is searching the slave.
1056	DNMXS_ScanListError	The Scan List has some errors.
1057	DNMXS_DeviceExist	The information of the slave device already exists.
1058	DNMXS_DeviceNotExist	The information of the slave device doesn't exist.
1059	DNMXS_MapTableError	The MapTable has some errors.

Table 4.2.3 Interpretation of the return code (I/O Error) 1/1

Return Code	MapTable Error	Comment
1100	DNMXS_ExplicitNotAllocate	The Explicit connection is not established.
1101	DNMXS_PollNotAllocate	The Poll connection is not established.
1102	DNMXS_BitStrobeNotAllocate	The Strobe connection is not established.
1103	DNMXS_COSNotAllocate	The COS connection is not established.
1104	DNMXS_CyclicNotAllocate	The Cyclic connection is not established.
1105	DNMXS_PollAlreadyExist	The Poll connection has been established.
1106	DNMXS_BitStrobeAlreadyExist	The Poll connection has been established.
1107	DNMXS_COSAlreadyExist	The COS connection has been established.
1108	DNMXS_CyclicAlreadyExist	The Cyclic connection has been established.
1109	DNMXS_CommunicationPause	The communication between PISO-DNM100(U) and all slave devices has been suspended.

Table 4.2.5 Interpretation of the return code (Slave Error) 1/1

Return Code	DeviceNet Error	Comment
1150	DNMXS_SlaveNoResp	The slave has no any response.
1151	DNMXS_WaitForSlaveResp	The PISO-DNM100(U) is waiting for the response form the slave device.
1152	DNMXS_SlaveRespError	The slave replied some errors.
1153	DNMXS_OutputDataLenError	The output length of the I/O connection doesn't match the device's output length.
1154	DNMXS_InputDataLenError	The input length of the I/O connection doesn't match the device's input length.

4.3 Function Description

4.3.1 DNM100_GetBoardInfo

- **Description:**

This function is used to obtain the driver information of PISO-DNM100(U) board.

- **Syntax:**

```
DWORD DNM100_GetBoardInf (BYTE BoardNo, DWORD *dwVID,  
                           DWORD *dwDID, DWORD *dwSVID,  
                           DWORD *dwSDID, DWORD *dwSAuxID,  
                           DWORD *dwIrqNo)
```

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

dwVID: [output] The address of a variable which is used to receive the vendor ID.

dwDID: [output] The address of a variable used to receive device ID.

dwSVID: [output] The address of a variable applied to receive sub-vendor ID.

dwSDID: [output] The address of a variable applied to receive sub-device ID.

dwSAuxID: [output] The address of a variable used to receive sub-auxiliary ID.

dwIrqNo: [output] The address of a variable used to receive logical interrupt number.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.2 DNM100_TotalDNM100Board

- **Description:**

The function can get the count of total PISO-DNM100(U) boards in the user's PC.

- **Syntax:**

DWORD DNM100_TotalDNM100board (BYTE *TotalBoards ,
BYTE *BoardIDList)

- **Parameter:**

TotalBoards: [output] The amount of total PISO-DNM100(U) boards.

BoardIDList: [output] The list of all DIP-Switch No. in each boards.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.3 DNM100_ActiveBoard

- **Description:**

The function is used to activate the PISO-DNM100(U) board. It must be called once before using the other functions of PISO-DNM100(U) APIs.

- **Syntax:**

DWORD DNM100_ActiveBoard (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.4 DNM100_CloseBoard

- **Description:**

The function is used to stop and close the kernel driver and release the device resource from computer device resource. This method must be called once before exiting the user's application program.

- **Syntax:**

DWORD DNM100_CloseBoard (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.5 DNM100_GetDLLVersion

- **Description:**

The function can obtain the version information of DNM100.DLL.

- **Syntax:**

DWORD DNM100_GetDLLVersion (void)

- **Parameter:**

None

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.6 DNM100_GetFirmwareVersion

- **Description:**

The function can obtain the version information of the firmware inside the PISO-DNM100(U) board.

- **Syntax:**

DWORD DNM100_GetFirmwareVersion (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

The firmware version information. For example: If 100(hex) is return, it means firmware version is 1.00.

- **Error Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.7 DNM100_ResetFirmware

- **Description:**

The function is used to reset the PISO-DNM100(U) firmware. When the users have changed the baud rate of CAN bus or changed the Master's MAC ID, the function must be called to make the change enable. After calling this function, the users should wait for 1 or 2 seconds to make the firmware boot up completely.

- **Syntax:**

DWORD DNM100_ResetFirmware (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.8 DNM100_GetMasterMACID

- **Description:**

The function can get the MAC ID of the DeviceNet master (PISO-DNM100(U)).

- **Syntax:**

DWORD DNM100_GetMasterMACID (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.9 DNM100_SetMasterMACID

- **Description:**

The function can set the MAC ID of the DeviceNet master (PISO-DNM100(U)). After calling this function, the users must call DNM100_ResetFirmware to make the change enabled. It will save the information in the EEPROM in the PISO-DNM100(U).

- **Syntax:**

DWORD DNM100_SetMasterMACID (BYTE BoardNo,
BYTE MasterMACID)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

MasterMACID: [input] The new MAC ID of the master. (0 ~ 63)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.10 DNM100_GetBaudRate

- **Description:**

This function can help you to get the DeviceNet baud rate information of PISO-DNM100(U).

- **Syntax:**

DWORD DNM100_GetBaudRate (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

The CAN bus baud rate information in the PISO-DNM100(U).

If the value is 0, the baud rate is 125Kbps.

If the value is 1, the baud rate is 250Kbps.

If the value is 2, the baud rate is 500Kbps.

- **Error Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.11 DNM100_SetBaudRate

- **Description:**

This function can set the DeviceNet baud rate of the PISO-DNM100(U). After calling this function, you must call DNM100_ResetFirmware to reset the firmware to make change enabled.

- **Syntax:**

DWORD DNM100_SetBaudRate (BYTE BoardNo,BYTE BaudRate)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

BaudRate: [input] The new baud rate value.

0 : 125K bps

1 : 250K bps

2 : 500K bps

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.12 DNM100_GetMasterStatus

- **Description:**

The function is used to obtain the firmware status inside the PISO-DNM100(U). The users can call this function to make sure that the DeviceNet master is online successfully.

- **Syntax:**

DWORD DNM100_GetMasterStatus (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.13 DNM100_GetSlaveStatus

- **Description:**

This function is to get the remote slave device's communication status.

- **Syntax:**

DWORD DNM100_GetSlaveStatus (BYTE BoardNo,
BYTE DesMACID)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DesMACID: [input] The remote slave's MAC ID. (0~63)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.14 DNM100_StartDevice

- **Description:**

This function is used to start to communicate with the specific device that the users applying to.

- **Syntax:**

DWORD DNM100_StartDevice (BYTE BoardNo, BYTE DesMACID)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DesMACID: [input] The remote slave's MAC ID. (0~63)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.15 DNM100_StopDevice

- **Description:**

This function is used to stop to communicate with the destination device that the users appointed to.

- **Syntax:**

DWORD DNM100_StopDevice (BYTE BoardNo, BYTE DesMACID)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.16 DNM100_StartAllDevice

- **Description:**

This function is used to start to communicate with all slave devices in ScanList.

- **Syntax:**

DWORD DNM100_StartAllDevice (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.17 DNM100_StopAllDevice

- **Description:**

This function is used to stop to communicate with all destination devices in ScanList.

- **Syntax:**

DWORD DNM100_StopAllDevice (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.18 DNM100_AddDevice

- **Description:**

This function can add the slave devices into the ScanList of the PISO-DNM100(U) and save the information into the EEPROM. Before communicating with any slave devices, the users should call this function to add these devices.

- **Syntax:**

DWORD DNM100_AddDevice (BYTE BoardNo, BYTE DesMACID,
WORD Explicit_EPR)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

Explicit_EPR: [input] The Expected Packet Rate. (Usually is 2500).

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.19 DNM100_RemoveDevice

- **Description:**

This function is used for removing the specified slave device from the ScanList in the PISO-DNM100(U). And the information of the device in EEPROM is erased at the same time.

- **Syntax:**

DWORD DNM100_RemoveDevice (BYTE BoardNo, BYTE DesMACID)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.20 DNM100_AddIOConnection

- **Description:**

This method is used to configure the I/O connection of the specific MAC ID device. The PISO-DNM100(U) can get/set the data via the connection, which connects to the specific slave, according to the produced / consumed connection path of this slave device. This configuration data will be saved into EEPROM within the PISO-DNM100(U).

- **Syntax:**

DWORD DNM100_AddIOConnection (BYTE BoardNo, BYTE DesMACID,
BYTE ConType,
WORD DeviceInputLen,
WORD DeviceOutputLen,
WORD EPR)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

ConType: [input] The remote slave device's I/O connection type

0 : Explicit connection type

1 : Poll connection type

2 : Bit-Strobe connection type

3 : COS connection type

4 : Cyclic connection type

DeviceInputLen: [input] The remote slave device's input length. (Byte)

DeviceOutputLen: [input] The remote slave device's output length. (Byte)

EPR: [input] The expected packet rate. (mSec)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.21 DNM100_RemoveIOConnection

- **Description:**

The function is used to remove the I/O connection configuration.

- **Syntax:**

DWORD DNM100_RemoveIOConnection (BYTE BoardNo,
BYTE DesMACID,
BYTE ConType)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

ConType: [input] The remote slave device's I/O connection type

0 : Explicit connection type

1 : Poll connection type

2 : Bit-Strobe connection type

3 : COS connection type

4 : Cyclic connection type

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.22 DNM100_GetAttribute

- **Description:**

This function is used to send the request command to retrieve the attribute value of the specific device's instance. Before calling this function, you must start the device. After calling this function, you should execute the "DNM100_GetAttributeValue" to get the response message returned from remote slave device.

- **Syntax:**

DWORD DNM100_GetAttribute (BYTE BoardNo, BYTE DesMACID,
BYTE ClassID, BYTE InstanceID,
BYTE AttributeID)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

ClassID: [input] The remote slave device's ClassID

InstanceID: [input] The remote slave device's InstanceID

AttributeID: [input] The remote slave device's AttributeID

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.23 DNM100_IsGetAttributeOK

- **Description:**

This function is used to check whether the PISO-DNM100(U) has received the response message or not. After checking the response message, you should execute the “DNM100_GetAttributeValue” to get the response message returned from remote slave device.

- **Syntax:**

DWORD DNM100_IsGetAttributeOK (BYTE BoardNo, BYTE DesMACID)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.24 DNM100_GetAttributeValue

- **Description:**

This function is used to get the attribute value of the specific device's instance from the remote slave device. Before calling this function, the users should call DNM100_GetAttribute to send request command first.

- **Syntax:**

DWORD DNM100_GetAttributeValue (BYTE BoardNo, BYTE DesMACID, WORD *DataLen, BYTE *DATA)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

DataLen: [output] The length of the attribute value (in byte).

DATA: [output] The attribute value that returned from the slave device.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.25 DNM100_SetAttribute

- **Description:**

The method is used to set the attribute of the specific device's instance. Before calling this function, you must start the device. After calling this function, you should execute the "DNM100_IsSetAttributeOK" to check the response message returned from the remote slave device.

- **Syntax:**

DWORD DNM100_SetAttribute (BYTE BoardNo, BYTE DesMACID,
BYTE ClassID, BYTE InstanceID,
BYTE AttributeID, WORD DataLen,
BYTE *DATA)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

ClassID: [input] The remote slave device's ClassID

InstanceID: [input] The remote slave device's InstanceID

AttributeID: [input] The remote slave device's AttributeID

DataLen: [input] The length of the attribute value (in byte).

DATA: [input] The attribute value that the users want to send.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.26 DNM100_IsSetAttributeOK

- **Description:**

This function is used to get the response value after executing the “DNM100_SetAttribute” function.

- **Syntax:**

DWORD DNM100_IsSetAttributeOK (BYTE BoardNo, BYTE DesMACID)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.27 DNM100_ClearAllConfig

- **Description:**

This function will clear all configurations in the EEPROM of the PISO-DNM100(U).

- **Syntax:**

DWORD DNM100_ClearAllConfig (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.28 DNM100_SearchAllDevices

- **Description:**

This function is used to retrieve all devices in DeviceNet network. Attention! This function will terminate all communications with remote devices. This function is usually used for developing or debugging applications.

- **Syntax:**

DWORD DNM100_SearchAllDevices (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.29 DNM100_SearchSpecificDevice

- **Description:**

This function is used to retrieve some devices which specified by the users. Attention! This function will terminate all communications with remote devices. This function is usually used for developing or debugging applications.

- **Syntax:**

DWORD DNM100_SearchSpecificDevice (BYTE BoardNo,
WORD ListCount,
BYTE *DesMACIDList)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

ListCount: [input] The amount of the slave's ID.

DestMACIDList: [input] The list of all slave's MAC ID.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.30 DNM100_IsSearchOK

- **Description:**

This function will check whether the searching process has finished or not.

- **Syntax:**

DWORD DNM100_IsSearchOK (BYTE BoardNo)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.31 DNM100_GetSearchedDevices

- **Description:**

This function will get the device which have been searched in the network

- **Syntax:**

```
DWORD DNM100_GetSearchedDevices (BYTE BoardNo,  
                                  WORD *TotalDevices,  
                                  BYTE *DesMACID,  
                                  BYTE *Type,  
                                  WORD *DeviceInputLen,  
                                  WORD *DeviceOutputLen)
```

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

TotalDevices: [output] The amount of all slave device which are found.

DesMACID: [output] The list of slave's MAC ID which are found.

Type: [output] The list of slave's connection type which are found.

0 : Explicit connection type

1 : Poll connection type

2 : Bit-Strobe connection type

3 : COS connection type

4 : Cyclic connection type

DeviceInputLen: [output] The list of slave's input length which are found.

DeviceOutputLen: [output] The list of slave's output length which are found.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.32 DNM100_GetDeviceInfoFromScanList

- **Description:**

This function will get the ScanList data of certain device in the PISO-DNM100(U).

- **Syntax:**

DWORD DNM100_GetDeviceInfoFromScanList
(BYTE BoardNo, BYTE DesMACID, WORD *ListCount,
BYTE *ConnectionTypeList, WORD *InputDataLenList,
WORD *OutputDataLenList, WORD *EPRList)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DesMACID: [input] The MAC ID number.

ListCount: [output] The amount of all information items.

ConnectionTypeList: [output] The list of slave's connection type.

0 : Explicit connection type

1 : Poll connection type

2 : Bit-Strobe connection type

3 : COS connection type

4 : Cyclic connection type

InputDataLenList: [output] The list of slave's input length.

OutputDataLenList: [output] The list of slave's output length.

EPRList: [output] The list of slave's expected packet rate.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.33 DNM100_GetScanList

- **Description:**

This function will get all the ScanList data in the PISO-DNM100(U).

- **Syntax:**

```
DWORD DNM100_GetScanList (BYTE BoardNo, WORD *TotalDevices,  
                           BYTE *DesMACIDList,  
                           BYTE *ConnectionTypeList,  
                           WORD *InputDataLenList,  
                           WORD *OutputDataLenList,  
                           WORD *EPR_List)
```

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

TotalDevices: [output] The data count of all the information.

DestMACIDList: [output] The MAC ID of all the slave devices in the ScanList.

ConnectionTypeList: [output] The connection type of all the slave devices in the ScanList.

0 : Explicit connection type

1 : Poll connection type

2 : Bit-Strobe connection type

3 : COS connection type

4 : Cyclic connection type

InputDataLenList: [output] The input data length of all the slave devices in the ScanList.

OutputDataLenList: [output] The output data length of all the slave devices in the ScanList.

EPR_List: [output] The EPR value of all the slave devices in the ScanList.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.34 DNM100_ImportEEPROM

- **Description:**

This function will write all specific devices' information in the ScanList to the EEPROM.

- **Syntax:**

DWORD DNM100_ImportEEPROM (BYTE BoardNo,
WORD ListCount,
BYTE *ConnectionTypeList,
WORD *InputDataLenList,
WORD *OutputDataLenList,
WORD *EPR_List)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

ListCount: [input] The data count of all the information.

ConnectionTypeList: [input] The connection type of all slave devices.

0 : Explicit connection type

1 : Poll connection type

2 : Bit-Strobe connection type

3 : COS connection type

4 : Cyclic connection type

InputDataLenList: [input] The input data length of all slave devices.

OutputDataLenList: [input] The output data length of all slave devices.

EPR_List: [input] The EPR value of all slave devices.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.35 DNM100_ReadInputData

- **Description:**

This function is to get the data according with the produced connection path of the specific MAC ID device via the I/O connection.

- **Syntax:**

DWORD DNM100_ReadInputData (BYTE BoardNo, BYTE DesMACID,
BYTE ConType, WORD *IOLen,
BYTE *IODATA)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

ConType: [input] The connection type of the remote slave.

0 : Explicit connection type

1 : Poll connection type

2 : Bit-Strobe connection type

3 : COS connection type

4 : Cyclic connection type

IOLen: [output] The length of the I/O data (In byte).

IODATA: [output] The remote I/O data.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.36 DNM100_WriteOutputData

- **Description:**

The function will set the data according with the consumed connection path of the specific MAC ID device via the I/O connection.

- **Syntax:**

DWORD DNM100_WriteOutputData (BYTE BoardNo, BYTE DesMACID,
BYTE ConType, WORD IOLen,
BYTE *IODETA)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

ConType: [input] The connection type of the remote slave.

0 : Explicit connection type

1 : Poll connection type

2 : Bit-Strobe connection type

3 : COS connection type

4 : Cyclic connection type

IOLen: [Input] The length of the I/O data (In byte).

IODETA: [Input] The remote I/O data.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.37 DNM100_SendExplicitMSG

- **Description:**

This function is used to send the explicit request command to retrieve or configure the attribute value of the specific device's instance. Before calling this function, you must start the device. After calling this function, you should execute the "DNM100_GetExplicitMSGRespValue" to get the response message returned from remote slave device.

- **Syntax:**

DWORD DNM100_SendExplicitMSG (BYTE BoardNo, BYTE DesMACID,
BYTE ServiceID, BYTE ClassID,
BYTE InstanceID,
WORD DataLen, BYTE *DATA)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

ServiceID: [input] The remote slave device's ServiceID.

ClassID: [input] The remote slave device's ClassID.

InstanceID: [input] The remote slave device's InstanceID.

DataLen: [input] The length of the attribute value (in byte).

DATA: [input] The attribute value that the users want to send.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.38 DNM100_IsExplicitMSGRespOK

- **Description:**

This function is used to check whether the PISO-DNM100(U) has received the response message or not. After checking the response message, you should execute the “DNM100_GetExplicitMSGRespValue” to get the response message returned from remote slave device.

- **Syntax:**

DWORD DNM100_IsExplicitMSGRespOK (BYTE BoardNo,
BYTE DesMACID)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.39 DNM100_GetExplicitMSGRespValue

- **Description:**

This function is used to get the attribute value of the specific device's instance from the remote slave device. Before calling this function, the users should call DNM100_SendExplicitMSG to send request command first.

- **Syntax:**

DWORD DNM100_GetExplicitMSGRespValue (BYTE BoardNo,
BYTE DesMACID,
WORD *DataLen ,
BYTE *DATA)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

DataLen: [output] The length of the attribute value (in byte).

DATA: [output] The attribute value that returned from the slave device.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.40 DNM100_ReadbackOutputData

- **Description:**

The function will read the data according with the consumed connection path of the specific MAC ID device via the I/O connection.

- **Syntax:**

DWORD DNM100_ReadbackOutputData (BYTE BoardNo,
BYTE DesMACID,
BYTE ConType,
WORD *IOLen,
BYTE *IODATA)

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15)

DestMACID: [input] The remote slave device's MAC ID (0~63)

ConType: [input] The connection type of the remote slave.

0 : Explicit connection type

1 : Poll connection type

2 : Bit-Strobe connection type

3 : COS connection type

4 : Cyclic connection type

IOLen: [output] The length of the I/O data (In byte).

IODATA: [output] The remote I/O data.

- **Return:**

Please refer to the chapter 4.2 for the function return code.

4.3.41 DNM100_ReadInputArea (Advanced Option)

- **Description:**

This function read the bulk data from the input area memory. Users can use this function to read all the input data quickly. It provides effective method to read the bulk data in one command. Please refer to the section 3.7 for more description.

- **Syntax:**

```
DWORD DNM100_ReadInputArea (BYTE BoardNo,  
                             WORD Offset,  
                             WORD DataLen,  
                             BYTE *DataArray)
```

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15).

Offset: [input] The offset of the input area memory.

DataLen: [input] The length in byte which the users want to read.

DataArray: [output] The data pointer of the obtained data from the input area memory.

- **Return:**

Please refer to the section 4.2 for the return code.

4.3.42 DNM100_WriteOutputArea (Advanced Option)

- **Description:**

This function can write the bulk data to the output area memory. The DeviceNet slave will change the output status of the DeviceNet slaves according to the data located in the output area memory. Users can use this function to write a large amount of the output data. It provides effective method to change bulk data in one command. Please refer to the section 3.7 for more description.

- **Syntax:**

```
DWORD DNM100_WriteOutputArea (BYTE BoardNo,  
                               WORD Offset,  
                               WORD DataLen,  
                               BYTE *DataArray)
```

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15).

Offset: [input] The offset of the input area memory.

DataLen: [input] The length in byte which the users want to read.

DataArray: [input] The data pointer pointed the data written to the output data area.

- **Return:**

Please refer to the section 4.2 for the return code.

4.3.43 DNM100_ReadbackOutputArea (Advanced Option)

- **Description:**

This function reads the bulk data from the output area memory. It does not change the output data located in the output area memory. Users can use this function to read back a large amount of the output data, but the data may be different with the real output statuses of the DeviceNet slaves. It provides effective method to read bulk data in one command. Please refer to the section 3.7 for more description.

- **Syntax:**

```
DWORD DNM100_ReadbackOutputArea (BYTE BoardNo,  
                                  WORD Offset,  
                                  WORD DataLen,  
                                  BYTE *DataArray)
```

- **Parameter:**

BoardNo: [input] PISO-DNM100(U) board number (0~15).

Offset: [input] The offset of the output area memory.

DataLen: [input] The length in byte which the users want to read.

DataArray: [output] The data pointer pointed the observed data from the output area memory.

- **Return:**

Please refer to the section 4.2 for the return code.

5. Demo Programs for Windows

All of demo programs will not work normally if PISO-DNM100(U) driver would not be installed correctly. During the installation process of the driver, the install-shields will register the correct kernel driver to the operation system and copy the DLL driver and demo programs to the correct position based on the driver software package you have selected (Win98,Me,NT,win2000,XP). After completing the driver installation, the related demo programs, development library and declaration header files for different development environments are installed in the system as follows.

The PISO-DNM100(U)'s root directory is C:\ICPDAS\PISO-DNM100

--\DLL	The DLL driver for the user's application
--\Driver	The window driver of the PISO-DNM100(U)
--\Manual	The user manual of the PISO-DNM100(U)
--\Demo	Demo program
--\Demo\BCB 6	Demos for Borland C++ Builder 6
--\Demo\VC++ 6	Demos for Visual C++ 6

5.1 A brief introduction to the demo programs

VC_Demo1 : Demonstrate the basic functions to communicate with the remote slave device. The demo program will lead you step by step to complete the setting and communication.

VC_Demo2 : Demonstrate the scan function to scan all the remote slave devices in the same DeviceNet network. The demo program will show you all the slave devices and their I/O connection type.

BCB_Demo1 : Demonstrate the scan function and add/remove function to configure the information of the remote slave device.

BCB_Demo2 : Demonstrate the I/O functions to access the I/O data of the remote slave device. The demo program will show you the input value of the remote device and let you send out the data to the output pins of the remote slave devices.

5.2 Wire Connection of the CAN bus

Before starting the demos, the users should have at least one slave device. Here show the users how to connect the master and slave devices by CAN bus. The slave devices should be connected to form the serial type which is shown as Figure 5.1

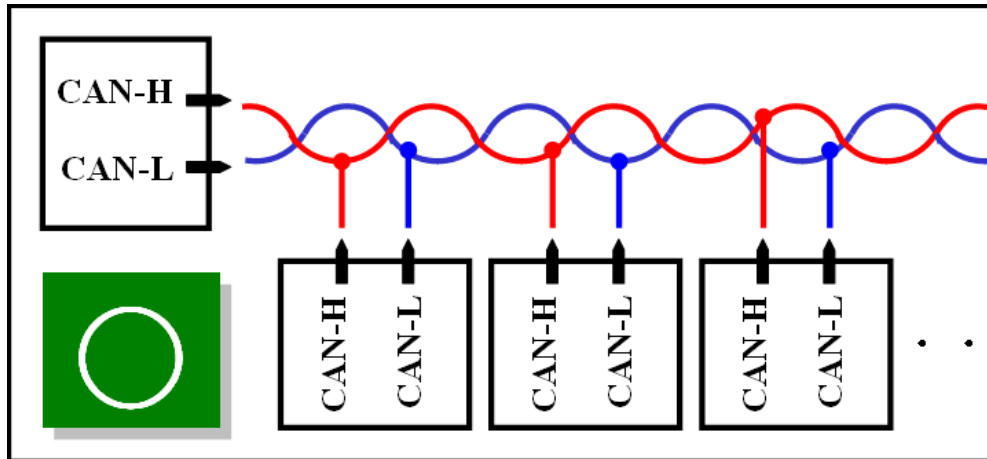


Figure 5.1 Correct wire connection

The following wire connection is **wrong** which is shown as Figure 5.2

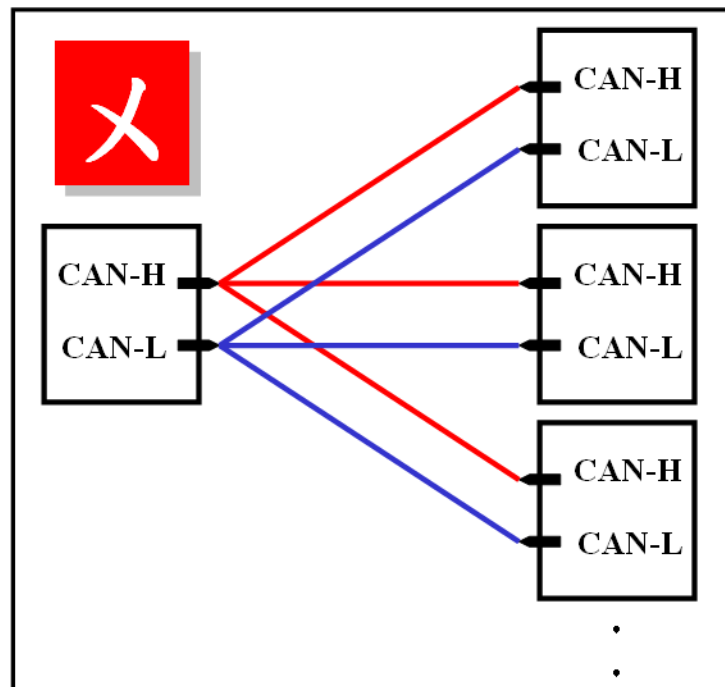


Figure 5.2 Wrong wire connection

5.3 VC_Demo1 Introduction

VC_Demo1 is the example used for starting the DeviceNet communication. The screen shoot is shown as Figure 5.3. This demo program is designed to communicate with slave devices step by step. This program will read the input value of the slave device when the POLL connection has been established. Before exercising this demo, the users should have at least one DeviceNet slave device which has input channels (AI or DI) and finish the wire connection between the Master and slave device. (See Figure 5.1)

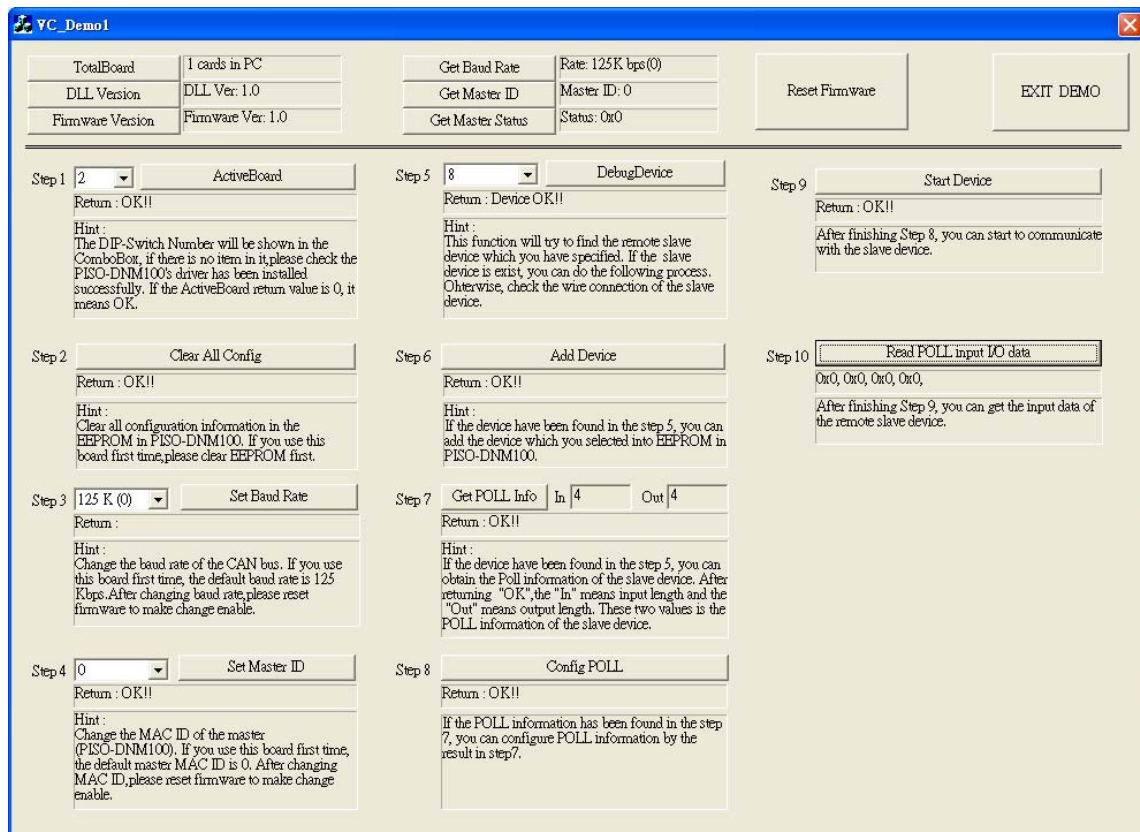


Figure 5.3 the screen shoot of VC_Demo1

After running the program, the users will see the “TotalBoards” information on the left and up corner of the screen. This function determinates how many PISO-DNM100(U) in your PC automatically. If the program doesn’t find any board, the users should check that the windows driver has been installed successfully. Otherwise, if it has found at lease one board, the users can continue exercising the demo program.

Step 1 : ActiveBoard

Before performing other buttons, the “ActiveBoard” button should be clicked firstly. The DIP-Switch on the board means the ID of this board. The users should make sure that every board’s ID in your PC is unique. The dropdown list will show the board’s ID which the users have selected. After clicking the button, the return code will be 0. Otherwise, please check the windows driver has been installed successfully.

Step 2 : Clear All Config

To avoid unknown configuration in the PISO-DNM100(U), the users can click this button to clear all configuration in the board.

Step 3 : Set Baud Rate

The default baud rate of DeviceNet is 125Kbps. If the users want to change the value, they can select the correct value then click the button. After changing the baud rate, the users should reset the firmware in the PISO-DNM100(U) by clicking the “ResetFirmware” button. It needs to wait for 1 or 2 seconds to the next step.

Step 4 : Set Master ID

The default Master’s MAC ID is 0. If the users want to change the value, you can select the correct value then click the button. After changing the Master’s ID, the users should reset the firmware in the PISO-DNM100(U) by clicking the “ResetFirmware” button. It needs to wait for 1 or 2 seconds to the next step.

Step 5 : Debug Device

Before performing this function, the users should set the MAC ID of the slave device and turn on it. In the demo, the users can select the MAC ID of the slave device then click “Debug Device” button. This function will try to find the appointed remote slave device waiting for 5 seconds, if the slave device exists in the network, the return value will be 0. Otherwise, the device doesn’t exist without response. The users can go to next step until the problem of the slave device has been solved.

Step 6 : Add Device

Before performing this function, the users should use step 5 to find an exist device. This function can add the device’s information found at step 5 into

EEPROM of the PISO-DNM100(U). If it is successful, the return value will be 0.

Step 7 : Get POLL Info

This function is to obtain the device's POLL information. After the slave device responses the data, it would show in the "In" and "Out". "In" means the input length of the slave device. "Out" means the output length of the slave device. If the slave device responses successfully, the return value will be 0.

Step 8 : Config POLL

If the step 7 is successful, the users can perform "Config POLL" button. This function is to add the device's POLL information into EEPROM in the PISO-DNM100(U). If it is successful, the return value will be 0.

Step 9 : Start Device

If the step 8 is successful, the users can perform "Start Device" button. This function would communicate with the slave device which the users have configured in the previous steps. If it is successful, the return value will be 0.

Step 10 : Read POLL Input I/O Data

If the master is communicating with the slave device successfully, the users can read the input I/O data from the slave device in this step. This function would obtain the input I/O data and show them in byte (8-bits).

5.4 VC_Demo2 Introduction

VC_Demo2 is the example used for scanning the DeviceNet slave devices in the network. The screen shoot is shown as Figure 5.4. This demo program is designed to operate the master step by step. This program will show the information of all the slave devices in the network. Before exercising this demo, the users should have at least one DeviceNet slave device and finish the wire connection between the Master and slave device. (See Figure 5.1)

No	MAC ID	IO Type	Input Len	Output Len
0	1	POLL	1	5
1	4	POLL	1	1
2	10	POLL	0	4
3	16	POLL	1	1
4	20	POLL	8	0
5	52	POLL	1	1
6	1	Bit-Strobe	1	0
7	4	Bit-Strobe	1	0
8	16	Bit-Strobe	1	0
9	20	Bit-Strobe	8	0
10	52	Bit-Strobe	1	0
11	1	OOS/Cyclic	1	0
12	4	OOS/Cyclic	1	0
13	8	OOS/Cyclic	4	0
14	16	OOS/Cyclic	1	0
15	20	OOS/Cyclic	8	0
16	18	OOS/Cyclic	8	0
17	22	OOS/Cyclic	8	0
18	32	OOS/Cyclic	4	0
19	34	OOS/Cyclic	1	0
20	52	OOS/Cyclic	1	0

Figure 5.4 The screen shoot of VC_Demo2

After running the program, the users will see the “TotalBoards” information on the left and up corner of the screen. This function determinates how many PISO-DNM100(U) in your PC automatically. If the program doesn’t find any board, the users should check that the windows driver has been installed successfully. Otherwise, if it has found at lease one board, the users can continue exercising the demo program.

Step 1 : ActiveModule

Before performing other buttons, the “ActiveBoard” button should be clicked firstly. The DIP-Switch on the board means the ID of this board. The users should make sure that every board’s ID in your PC is unique. The dropdown list will show the board’s ID which the users have selected. After clicking the button, the return code will be 0. Otherwise, please check the windows driver has been installed successfully.

Step 2 : Set Baud Rate

The default baud rate of DeviceNet is 125Kbps. If the users want to change the value, they can select the correct value then click the button. After changing the baud rate, the users should reset the firmware in the PISO-DNM100(U) by clicking the “ResetFirmware” button. It needs to wait for 1 or 2 seconds to the next step.

Step 3 : Auto Scan Network

Before performing this function, the users should set the MAC ID and the baud rate of the slave device and turn on it. In the demo, the user can click “Auto Scan Network” button to obtain all the I/O information of all slave devices in the network. The scan procedure needs about 30 seconds. The users will see the entire slave device in the network and their I/O information in the list table.

5.5 BCB_Demo1 Introduction

BCB_Demo1 is the example used for scanning the DeviceNet slave devices in the network. The screen shoot is shown as Figure 5.5. This program will show the information of all the slave devices. This demo is similar to VC_Demo2. Before exercising this demo, the users should have at least one DeviceNet slave device and finish the wire connection between the Master and slave device. (See Figure 5.1) The users can configure the slave device by the scanning information. This demo can be a tool to add or remove the configuration of the slave device.

Form1

Total PISO-DNM100 : 1 DLL Ver : 100 Master Status :

Board ID 2 Active Board OK Firmware Ver : 100

Reset Firmware ClearAllConfig LoadScanList Baud Rate :

AutoScan Total: 29 Master ID :

No.	MAC ID	I/O Type	Input Len	Output Len
<input type="checkbox"/> 0	4	Poll	1	1
<input type="checkbox"/> 1	1	Poll	1	5
<input type="checkbox"/> 2	10	Poll	0	4
<input type="checkbox"/> 3	16	Poll	1	1
<input type="checkbox"/> 4	18	Poll	8	0
<input type="checkbox"/> 5	22	Poll	8	1
<input type="checkbox"/> 6	20	Poll	8	0
<input type="checkbox"/> 7	32	Poll	4	0
<input type="checkbox"/> 8	34	Poll	1	1
<input type="checkbox"/> 9	52	Poll	1	1
<input type="checkbox"/> 10	4	BitStrobe	1	0

Scan Table

Add Device Remove Device

No.	MAC ID	I/O Type	Input Len	Output Len
<input type="checkbox"/>	8	Poll	4	4

Configure Table

Figure 5.5 The screen shoot of BCB_Demo1

After running the program, the users would see the “Total PISO-DNM100(U) : x” information on the left and up corner of the screen. This function determinates how many PISO-DNM100(U) in your PC automatically. If the program doesn’t find any board, the users should check that the windows driver has been installed successfully. Otherwise, if it has found at lease one module, the users can continue exercising the demo program.

Step 1 : Active Module

Before performing other buttons, the “ActiveBoard” button should be clicked firstly. The DIP-Switch on the board means the ID of this board. The users should make sure that every board’s ID in your PC is unique. The dropdown list will show the board’s ID which the users have selected. After clicking the button, the return code will be 0. Otherwise, please check the windows driver has been installed successfully.

Step 2 : Auto Scan

Before performing this function, the users should set the MAC ID and the baud rate of the slave device and turn on it. In the demo, the user can click “Auto Scan Network” button to obtain all the I/O information of all slave devices in the network. The scan procedure needs about 30 seconds. The users will see the entire slave device in the network and their I/O information in the “Scan Table”.

Step 3 : Add Device

This function is to add the device’s information into EEPROM in the PISO-DNM100(U). The users can check the item which you want to add. After checking what you want, push “Add Device” button to add the information into the EEPROM. If it is successful, the items which you selected will be shown in the “Configure Table”.

Step 4 : LoadScanList

This function is to obtain the device’s information from EEPROM in the PISO-DNM100(U). The users can check the information in the EEPROM. After performing the function, the information will be shown in the “Configure Table”.

5.6 BCB_Demo2 Introduction

BCB_Demo2 is the extension of the BCB_Demo1. The screen shoot is shown as Figure 5.6. This program can read the input data and write the output data in every second. This demo is similar to BCB_Demo1. We just introduce the extension part. Before exercising this demo, the users should have at least one DeviceNet slave device and finish the wire connection between the Master and slave device. (See Figure 5.1) The users can configure the slave device by the scanning information. This demo can be a tool to add or remove the configuration of the slave device. Additionally, the users can operate the I/O data form the remote slave devices.

Form1

Total PISO-DNM100 : 1 DLL Ver : 100 Master Status : 0

Board ID : 2 Active Board OK Firmware Ver : 100

Reset Firmware ClearAllConfig LoadScanList Baud Rate : 0

AutoScan Total: 29 Master ID : 0

No.	MAC ID	I/O Type	Input Len	Output Len
<input type="checkbox"/> 0	1	Poll	1	5
<input type="checkbox"/> 1	4	Poll	1	1
<input type="checkbox"/> 2	10	Poll	0	4
<input type="checkbox"/> 3	16	Poll	1	1
<input type="checkbox"/> 7	32	Poll	4	0
<input type="checkbox"/> 8	34	Poll	1	1
<input type="checkbox"/> 9	52	Poll	1	1
<input type="checkbox"/> 10	1	BitStrobe	1	0
<input type="checkbox"/> 11	4	BitStrobe	1	0
<input type="checkbox"/> 12	16	BitStrobe	1	0
<input type="checkbox"/> 13	18	BitStrobe	8	0

Scan Table

Add Device Remove Device

No.	MAC ID	I/O Type	Input Len	Output Len
<input type="checkbox"/> 8	8	Poll	4	4
<input type="checkbox"/> 18	18	Poll	8	0
<input type="checkbox"/> 22	22	Poll	8	1
<input type="checkbox"/> 20	20	Poll	8	0

Configure Table

MAC_ID : 8 1 4 4 ☒ Enable/Disable

Output : 47

Input : 0, 0, 0, 0,

MAC_ID : 18 1 8 0 ☒ Enable/Disable

Output :

Input : F5,3F,F7,3F,F9,3F,F7,3F,

MAC_ID : 22 1 8 1 ☒ Enable/Disable

Output :

Input : 0, 0, 0, 0, 0, 0, 0,

MAC_ID : 20 1 8 0 ☒ Enable/Disable

Output :

Input : 35, 0, 35, 0, 2F, 0, 33, 0,

MAC_ID : 1 2 2 ☐ Enable/Disable

Output :

Input : Edit1

MAC_ID : 1 2 2 ☐ Enable/Disable

Output :

Input : Edit1

Figure 5.6 The screen shoot of BCB_Demo2

If the users want to know how to configure the slave device information into EEPROM in the PISO-DNM100(U), please refer to section 5.5.

If “Active Board” is OK, the users can click “LoadScanList” button. The configuration information will be shown in “Configure Table”. At the same time, the MAC IDs also are shown on the right side of the screen. The users can check the “Enable/Disable” box to enable or disable the read and write the I/O data. The “Output” scroll bar presents the output value which will be written to the output channel of the slave device. If the scroll value is 0x23, every byte of the slave device’s output is 0x23. The users can find out the change of the output channel easily. The “Input” field presents the input value from the input channel of the slave device.

6. LabVIEW Driver Introduction

6.1 Software Installation

The PISO-DNM100(U) LabVIEW 8.x driver is the PISO-DNM100(U) function reference for the DeviceNet master device used on LabVIEW 8.x environment on Windows 2000/XP. Before users use this driver to develop the machine control system, the PISO-DNM100(U) driver must be installed first, because the PISO-DNM100(U) LabVIEW 8.x driver needs to call the function of it. The driver architecture is shown as Figure 6.1.

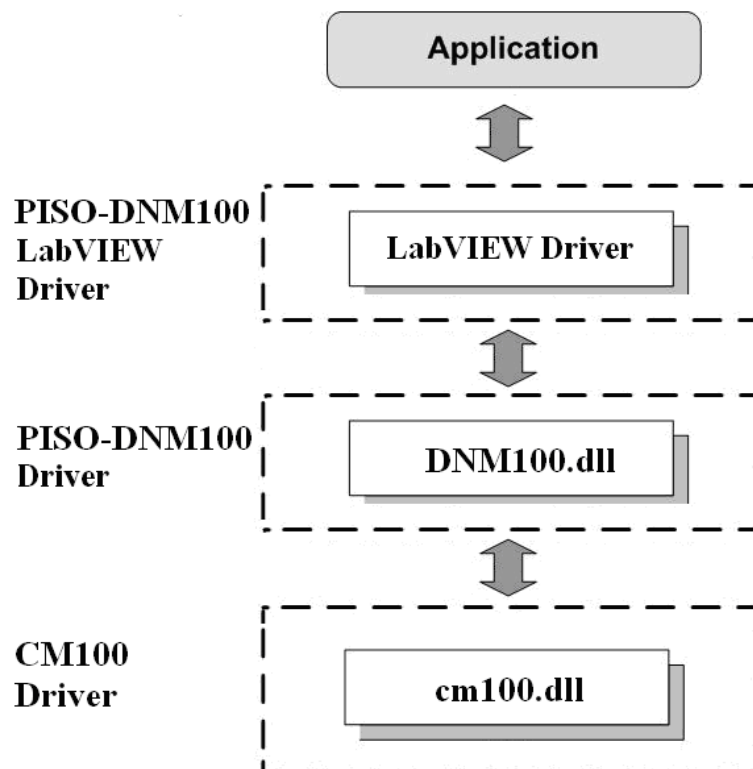


Figure 6.1 Driver concept of PISO-DNM100(U) LabVIEW driver

After completing the LabVIEW driver installation, the directory of PISO-DNM100(U) LabVIEW Driver is C:\ICPDAS\PISO-DNM100\LabVIEW.

|--\Driver LabVIEW driver
|--\Demo LabVIEW demo program

PISO-DNM100(U) LabVIEW Function palette is showed as below.

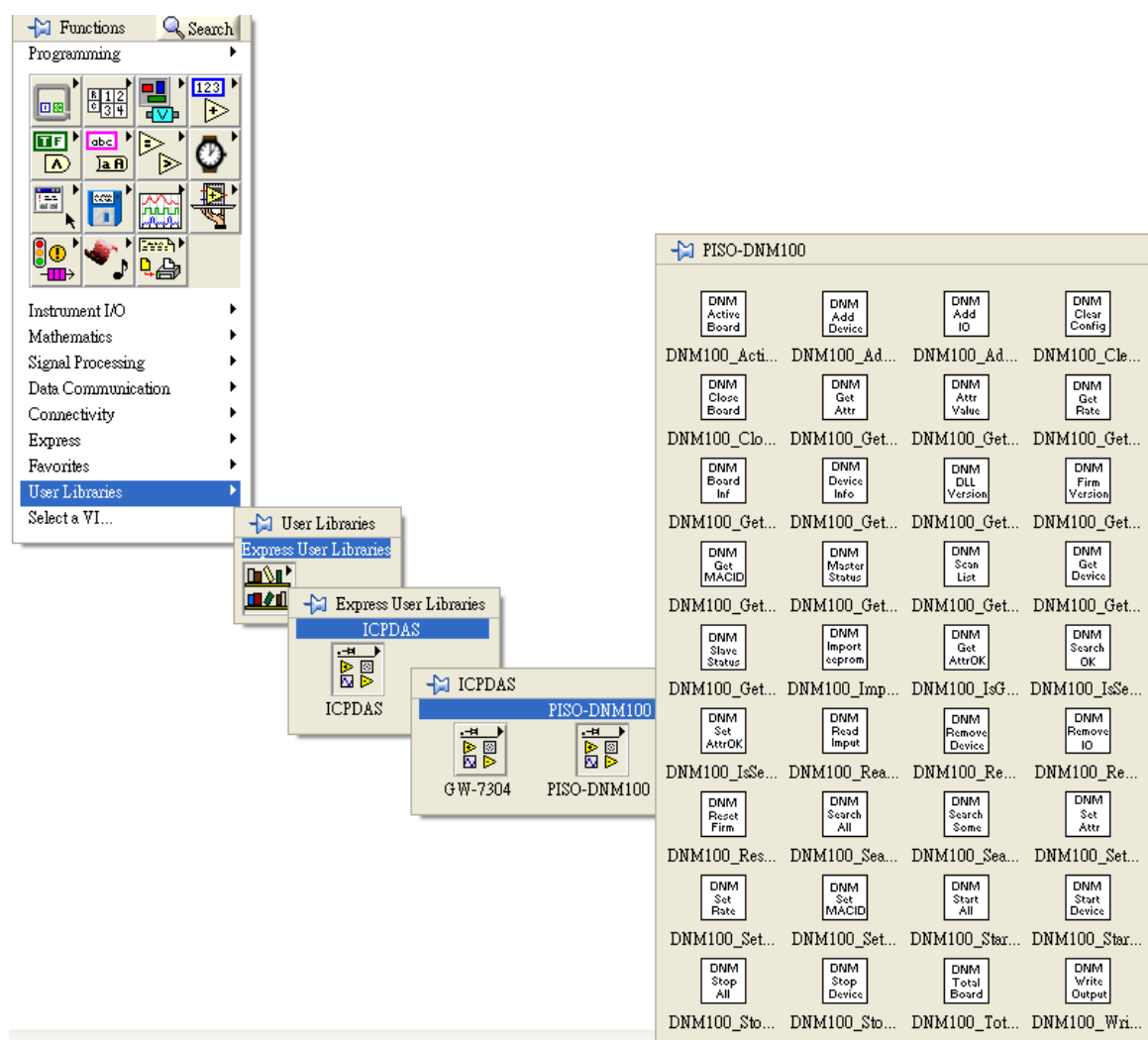


Figure 6.2 PISO-DNM100(U) LabVIEW Function palette

6.2 Function description

Every function provides each VI for user to use in the LabVIEW environment. All the functions provided by the DNM100.dll are listed in the following table.

Table 6.2.1 Board Functions






No.	VI ICON	Function Name	Description
1		DNM100_GetBoardInf	Get the driver information of the PISO-DNM100(U)
2		DNM100_TotalDNM100Board	Get total PISO-DNM100(U) boards in the PC
3		DNM100_ActiveBoard	Enable the driver of the PISO-DNM100(U)
4		DNM100_CloseBoard	Close driver of the PISO-DNM100(U)
5		DNM100_GetDLLVersion	Get the DLL version of the DNM100.DLL

Table 6.2.2 Firmware Functions



No.	VI ICON	Function Name	Description
1		DNM100_GetFirmwareVersion	Get the version of the firmware inside the PISO-DNM100(U) board
2		DNM100_ResetFirmware	Reset the firmware in the PISO-DNM100(U) board

Table 6.2.3 Operating Functions 1/3




No.	VI ICON	Function Name	Description
1		DNM100_SetMasterMACID	Set the MAC ID of the PISO-DNM100(U) board (DeviceNet Master's MAC ID)
2		DNM100_GetMasterMACID	Get the MAC ID of the PISO-DNM100(U) board (DeviceNet Master's MAC ID)
3		DNM100_GetBaudRate	Get the baud rate of the CAN bus

Table 6.2.4 Operating Functions 2/3








No.	VI ICON	Function Name	Description
17		DNM100_GetAttributeValue	Get the attribute value of the DNM100_GetAttribute
18		DNM100_SetAttribute	Send the set attribute command to the slave device.
19		DNM100_IsSetAttributeOK	Check whether the slave has replied for the setting command or not.
20		DNM100_GetDeviceInfoFromScanList	Get specific slave device's I/O information from the Scan List within the PISO-DNM100(U) board.
21		DNM100_GetScanList	Get the I/O information of all slave devices from the Scan List within the PISO-DNM100(U) board.
22		DNM100_ImportEEPROM	Write the I/O information of all slave devices into the EEPROM within the PISO-DNM100(U) board.
23		DNM100_ClearAllConfig	Clear all configurations in the EEPROM within the PISO-DNM100(U) board.

Table 6.2.5 Operating Functions 3/3














No.	VI ICON	Function Name	Description
4		DNM100_SetBaudRate	Set the baud rate of the CAN bus
5		DNM100_GetMasterStatus	Get the status of the PISO-DNM100(U) board (DeviceNet Master's status) at present
6		DNM100_GetSlaveStatus	Get the slave device's status.
7		DNM100_StartDevice	PISO-DNM100(U) will start to communicate with the specific slave device
8		DNM100_StopDevice	PISO-DNM100(U) will stop to communicate with the specific slave device
9		DNM100_StartAllDevice	PISO-DNM100(U) will start to communicate with all slave devices
10		DNM100_StopAllDevice	PISO-DNM100(U) will stop to communicate with all slave devices
11		DNM100_AddDevice	Add the specific slave device's information into the PISO-DNM100(U) board (DeviceNet Master)
12		DNM100_RemoveDevice	Remove the specific slave device's information from the PISO-DNM100(U) board (DeviceNet Master)
13		DNM100_AddIOConnection	Add I/O information of the specific slave device into the PISO-DNM100(U) board (DeviceNet Master)
14		DNM100_RemoveIOConnection	Remove specific slave device's I/O information from the PISO-DNM100(U) board (DeviceNet Master)
15		DNM100_GetAttribute	Send the get attribute command to the slave device.
16		DNM100_IsGetAttributeOK	Check whether the slave has replied for the getting command or not.

Table 6.2.6 Searching Functions







No.	VI ICON	Function Name	Description
1		DNM100_SearchAllDevices	PISO-DNM100(U) will search the DeviceNet network to find out the I/O information of all slave devices.
2		DNM100_SearchSpecificDevice	PISO-DNM100(U) will search the DeviceNet network to find out the I/O information of specific slave devices.
3		DNM100_IsSearchOK	Check whether the PISO-DNM100(U) has searched completely or not.
4		DNM100_GetSearchedDevices	Get the result of the searching command and retrieve the slave's I/O information.

Table 6.2.7 I/O Functions

No.	VI ICON	Function Name	Description
1		DNM100_ReadInputData	Read the input data via I/O connection like Poll, Strobe, COS, Cyclic.
2		DNM100_WriteOutputData	Write the output data via I/O connection like Poll, COS, Cyclic. The Strobe doesn't support this operation.

6.3 LabVIEW Demo Introduction

The LabVIEW Demo is similar to the VC_Demo1. The screen shoot is shown as Figure 6.3.1. This demo program is designed to communicate with slave device step by step. All operating steps and detail descriptions can see in the section 5.3.

The screenshot displays a LabVIEW Demo interface with 11 steps for configuring and communicating with a slave device. Each step includes a title, a button, a return value field, and a descriptive text box.

- Step1:** Active Board. Return: 0. Description: The module number will be shown in the ComboBox, if there is no item in it, please check the I-7565-DNM's driver has been installed successfully. If the ActiveBoard return value is 0, it means OK.
- Step2:** Clear All Config. Return: 0. Description: Clear all configuration information in the EEPROM in I-7565-DNM. If you use this board first time, please clear EEPROM first.
- Step3:** Set Baud Rate. Return: 0. Description: Change the baud rate of the CAN bus. If you use this board first time, the default baud rate is 125 Kbps. After changing baud rate, please reset firmware to make change enable.
- Step4:** Set Master ID. Return: 0. Description: Change the MAC ID of the master (I-7565-DNM). If you use this board first time, the default master MAC ID is 0. After changing MAC ID, please reset firmware to make change enable.
- Step5:** Debug Device. Return: 0. Description: This function will try to find the remote slave device which you have specified. If the slave device is exist, you can do the following process. Otherwise, check the wire connection of the slave device.
- Step6:** Add Device. Return: 0. Description: If the device has been found in the step 5, you can add the device which you selected into EEPROM in I-7565-DNM.
- Step7:** Get POLL Info. Return: In 0, Out 0. Description: If the device has been found in the step 5, you can obtain the Poll information of the slave device. After returning "OK", the "In" means input length and the "Out" means output length. These two values is the POLL information of the slave device.
- Step8:** Config POLL. Return: 0. Description: If the POLL information has been found in the step 7, you can configure POLL information by the result in step7.
- Step9:** Start Device. Return: 0. Description: After finishing Step 8, you can start to communicate with the slave device.
- Step10:** Read POLL input IO data. Return: IODATA. Description: After finishing Step 9, you can get the input data of the remote slave device.
- Step11:** Write POLL output IO data. Return: 0. Description: After finishing Step 9, you can send the output data to the remote slave device.

At the bottom right, there is a section for "Total Board : 0" with a green indicator light, and buttons for "Get Baud Rate", "Reset Firmware", and "EXIT".

Figure 6.3.1 The screen shoot of LabVIEW Demo